## SECTION I

## CRANE INSTALLATION INSTRUCTIONS

CRANE INSTALLATION INSTRUCTIONS
.F2728-C
1-1

MOUNTING PATTERN.........................................................................DWG.50653-C.............................................. 1-3
ELECTRICAL INSTALLATION
DWG.50948-0.
1-4
HYDRAULIC INSTALLATION ...................................................DWG.50026-C ........................... 1-5
ENGINE CONTROL RECEIVER INSTALLATION...................F1214-E..................................... 1-6
STABILITY PROCEDURE.........................................................F691-I......................................... 1-7
STABILITY TEST RESULTS ......................................................F691-I.......................................... 1-8
SECTION II
GENERAL OPERATION, INSPECTION, AND MAINTENANCE

CRANE SAFETY RULES...........................................................F1122-C..................................... 2-1
INTRODUCTION .......................................................................F1111-D...................................... 2-3
OPERATING RESTRICTIONS ....................................................F1112-G ..................................... 2-4
OPERATING PRACTICES ..........................................................F1112-G ..................................... 2-4
INSPECTION AND MAINTENANCE.......................................F1113-E..................................... 2-7
MONTHLY INSPECTION REPORT ..........................................F1123-B..................................... 2-9
ANNUAL INSPECTION REPORT..............................................F1507-0 .................................... 2-10
STANDARD HAND SIGNALS FOR CRANE OPERATIONS ..F2409-0 .................................... 2-13

## SECTION III

WIRELESS REMOTE-CONTROL SYSTEM
OPERATION MANUAL RADIO/CAN REMOTE WIFI
.F2724-0
3-1

DIAGNOSTIC GATE AND SOFTWARE DATES .....................F2795-B ................................... 3-36
SECTION IV
CRANE SYSTEMS AND TROUBLESHOOTING
SAFETY SYSTEM......................................................................F1769-A .................................... 4-2

PROPORTIONAL HYDRAULIC SYSTEM.................................F2817-0 ...................................... 4-3
BASIC TROUBLESHOOTING CHART .....................................F1774-0 ..................................... 4-5
TROUBLESHOOTING PROPORTIONAL SYSTEMS ...............F1447-C .................................... 4-6
DEUTSCH CONNECTORS AND PINS.......................................F2435-A ..................................... 4-7

## SECTION V

## CRANE SPECIFICATIONS

LIFTING CAPACITIES ................................................................F2651-C ...................................... 5-1
POWER FUNCTIONS AND SPEEDS.........................................F2651-C .................................... 5-1
BOLT AND LUBRICATION SPECS ............................................F2651-C ..................................... 5-2
CRANE LUBRICATION POINTS..............................................F2651-C .................................... 5-3
SECTION VI
PARTS
BOX PARTS LIST F2726-A ..... 6-1
CRANE ASSEMBLY \& ELEC SCHEMATIC DWG.29606-I ..... 6-2
BOOM-BODY ASSEMBLY DWG.29545-C. ..... 6-10
ELEVATION CYLINDER ASSEMBLY DWG.21521-E ..... 6-12
BODY ASSEMBLY .DWG.29541-C ..... 6-13
MANIFOLD ASSEMBLY DWG.29575-C ..... 6-15
MANIFOLD PRE-ASSEMBLY .DWG.24993-D ..... 6-16
BASE HOUSING ASSEMBLY DWG.29880-C ..... 6-17
HYDRAULIC SWIVEL .DWG.29801-E ..... 6-21
EWH, DUAL SWIVEL HYD/ELEC .DWG.29824-D ..... 6-23
BOOM ASSEMBLY - 30 FT. .DWG.29235-C ..... 6-24
BOOM OUTER ASSEMBLY - 30 FT DWG.29233-D ..... 6-26
BOOM INNER ASSEMBLY - 30 FT DWG.27575-G ..... 6-27
WINCH .DWG.29086-0 ..... 6-28
ROTATION SPEED REDUCER DWG.29116-B ..... 6-32
ELECTRICAL WIRING HARNESS .DWG.29547-H ..... 6-34
HYDRAULIC SCHEMATIC DWG.50949-B ..... 6-37
TRAVEL BLOCK ASSY DWG.29259-B ..... 6-38
FM CONTROL SYSTEM DWG.29695-C ..... 6-39

## MODEL 6040/8045 INSTALLATION INSTRUCTIONS

Read and understand these instructions completely before starting the work.
Before installing make sure you have all necessary parts. Please refer to the Owner's manual Section 6-1 for the list of parts required for installation. Report any shortages to Liftmoore, Inc. immediately.

1. The mounting surface for the crane must be capable of supporting the rated moment and maximum load of the crane listed below:

$$
\begin{array}{lll}
6040 \text { CRANE } & 40,000 \text { Ft.-Lbs. } & 6,000 \text { Lbs. } \\
8045 \text { CRANE } & 45,000 \text { Ft.-Lbs. } & 8,000 \text { Lbs. }
\end{array}
$$

2. Layout the mounting holes for the crane as shown in the drawing No. 50653. Cut the center hole for the crane swivel as shown on this drawing. Mount the crane with four $7 / 8-9$ " Grade 8 quality and dry torque to 600 ft -lbs.
3. A manual disconnect switch with mounting bracket and terminals is provided with the crane. This switch will act as the main electric power disconnect for the crane. Removing power from the crane during periods of non-use will increase the life of the crane's electrical components. The switch should be mounted as near as possible to the crane and in a position which will facilitate its use. Determine the appropriate mounting position for the switch and use the supplied terminals to splice into the crane's main power cable. Drawing No. 50948 illustrates how to install the disconnect switch and fuse.
4. Install the 30 Amp fuse, which is supplied with the crane, near the battery on the positive line. This fuse is to protect the wiring in event of an accidental grounding. Use a section of the wire and the terminals supplied to connect between the battery and the circuit breaker. See drawing No. 50948.
5. Run the 10 Ga . battery cables (red and black wires) along the inside of the chassis frame to the battery. Connect the (+ red wire) battery cable to the in-line fuse and the (- black wire) to the negative terminal with the terminals provided. See that the cable is protected. Avoid sharp edges and heat sources such as the muffler or catalytic converter. Use loom for protection whenever the cable passes through the body. On continuous rotation models, use the terminal supplied with the wires and connect the cables to the mating terminal underneath the crane located between the pipe nipples in the center of the swivel. See dwg No. 50948.
6. A good tight ground connection to the negative terminal power source must exist for the crane to work.
7. Hydraulic Component Installation: The following description applies to Liftmoore's Hydraulic Installation Drawing No. 50026.

These cranes require a pump driven by the vehicle's engine. Pumps can be either Power Take Off or Fan Belt drive. For best, smoothest operation the pump needs to supply 8 GPM at 3,000 PSI with the engine at 1,000 RPM.

Do not use pumps that will deliver more than 8 GPM at engine speed. 10 GPM is the maximum flow acceptable to the valves in the crane. If a larger pump is installed on the vehicle for other functions, use a pressure compensated flow control valve to restrict the flow to the crane as required above.

The Liftmoore WP crane transmitter has two switches designated engine start and stop, engaging high idle, and additional control of auxiliary equipment. An optional receiver is required that will enable these functions. Please see the Liftmoore Product List at www.liftmoore.com for additional information.

A reservoir capacity 12 gallon minimum is recommended. The reservoir capacity will need to be enlarged for increased running time. For run times of 15 minutes or less the 12 gallon capacity is adequate. For longer duty cycles the reservoir size should be increased and an oil cooler should be considered.
8. DO NOT RUN OIL THROUGH THE CRANE UNTIL THE OIL HAS BEEN FILTERED. An adapter union matching the crane fittings is included. Connect the supply and return lines together using this adapter, circulate the oil through the filter to insure a clean supply. After the pump has filtered 1.5 times the reservoir capacity, hook the hoses to the crane. It is now ready to run.
9. Connect the hydraulic hoses to the fittings projecting below the crane. The pressure hose must be connected to the port marked "P" (No. 8 size fitting). This is the smaller of the two fittings. The return line to the tank must be connected to the port marked "T" (No. 10 fitting). This is the larger of the two fittings. The port letters are stamped on the bottom of the swivel.
10. Verify that the anti two-block will stop extension out and winch up when the Bail arms device is lifted by either function. The Crane Assembly drawing in the owner's manual illustrates how the Bail arms should be installed on the crane.
11. READ AND UNDERSTAND OPERATORS MANUAL BEFORE OPERATING CRANE. Operate the crane through all its functions. Check that each switch operates the correct function. Verify speed of the unit.
12. A boom support is required for this crane. For bodies shorter than $132^{\prime \prime}$, place the support so that the traveling block hook is secured and does not block the truck cab door.
13. An outrigger rated at least that of the crane must be installed to keep the crane as level as possible under all expected working conditions. Keeping the crane level reduces the loads on the rotation gear. This will also protect the truck's springs, axle, and wheels when heavy loads are suspended from the crane. OSHA requirements require a stability test be performed on this installation.
14. Extra rear spring leaves or heavy coil springs may be needed to keep the truck level when the crane is mounted on corner or off center locations.
15. Place these instructions with the Operators Manual.
16. Load Chart and stability test decals are to be placed on the truck body for easy visibility by the user.



## OPTIONAL ENGINE CONTROL RECEIVER INSTALLATION

The engine control functions allow the user to start and stop the engine and also advance the idle, all from the crane remote pendant control.

The following instructions provide a general guideline for installing and wiring the receiver. Since engine controls vary from manufacture to manufacturer and even from year to year, it is impossible for Liftmoore to maintain specific information on your vehicle. You will have to contact the vehicle and/or engine manufacturer (contact information is provided below). Also, many new vehicles have a provisions for remote engine control built into the ECU, but these functions must be activated and/or programmed by a dealer or authorized service center.

## MOUNTING THE RECEIVER

The receiver should be mounted vertically with the antenna up. For best reception, it should be mounted in cab in line of site of operator. Since interfacing connections will generally be inside the cab, a good mounting place is the inside, back the cab with the antenna visible though the back glass. The receiver can be mounted outside of the cab, however it should NOT be mounted inside the engine compartment because of interference generated by the engine.

## ENGINE START

Engine start is accomplished by splicing the brown wire on the engine receiver control harness with the ECU start circuit.


#### Abstract

WARNING! Engine start may bypass some manufactures safety functions such as clutch or neutral interlock. It is the installer's responsibility to ensure safe and proper installation.


## ENGINE STOP

If the ECU is not equipped with a remote engine kill circuit then a normally closed relay must be installed in the ECU power or engine run circuit. The gray wire on the engine control receiver harness is then connected to the solenoid coil. Activating the circuit will open the solenoid, killing the engine.

## NOTE!

It is advisable to include a small jumper wire that can be installed to bypass the solenoid should it fail, otherwise the engine would not run.

## ADVANCED IDLE

Many new diesel engines have an advanced idle control circuit built into to the ECU. Some automatically advance the idle when the PTO is activated. This feature may have to be activated and/or programmed by the dealer.

## NOTE!

Some engines also require activating a PTO circuit to prevent "Service Engine Soon" or other erroneous errors during PTO operation.

For gas engines or engines without this feature, an after-market throttle advance will have to be purchased separately.

## CONTACT INFORMATION

Your truck or engine dealer should be able to provide you with further assistance. Also check the manufacturer's body builder manual (some provided online). Before calling, please have your vehicles make, model, year, engine and transmission size and manufacturer, and VIN if available.

| Ford Body Builders Advisory Service | 1.877 .840 .4338 |
| :--- | ---: |
| GM Upfitter Integration | 1.800 .875 .4742 |
| Peterbilt | 1.940 .591 .4000 |
| Caterpillar | 1.800 .847 .4986 |
| Cummins | 1.800 .343 .7357 |
| RAM |  |
| Navistar | 1.800 .365 .0088 |

fordbbas.com/home
gmupfitter.com/body-builder-manuals
ramtrucks.com/ram-commercial/body-builders-guide bodybuilder.navistar.com

## VEHICLE STABILITY TEST

OSHA (29CFR 1910.180c) requires a stability test be completed by the installer. A qualified person shall perform this test. Please call Liftmoore for any assistance required in completing this test.

## TEST PREPARATIONS:

- Use as level of a test site as possible.
- Engage parking brake on vehicle.
- Set outriggers, jackstands, or other stability device in place.
- Vehicle tires should remain in contact with the ground.
- The vehicle should be level.


## FILL OUT TEST FORM:

- Complete the Vehicle Information and Crane Information data at the top of Page 2 of this form.
- Use a known weight to determine the Initial Testing Load Radius. Write this number on all 3 locations on Page 2 of this form.


## TEST PROCEDURE:

## Determine Area Y Angle

1. With the crane extended to the Initial Testing Load Radius over the rear of the truck, lift the load. Keep the load less than 4 " off of the ground.
2. Rotate the load counterclockwise. Monitor all vehicle tires to ensure they remain in contact with the test surface.
3. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
4. Use a protractor to determine this angle. Write this angle on the Stability Test Results as Area Y.

## Determine Area W1 Length

5. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
6. Continue rotating the load counterclockwise while monitoring all vehicle tires.
7. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
8. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
9. Repeat this procedure until either the vehicle prevents further rotation or a 180 degree rotation of the load is reached.
10. Record the load radius in feet at this point on page 2 of this form as Area W1 Length.
11. Calculate the W1 \% Rated Capacity.
12. Write the W1 \% Rated Capacity in the Stability Test Results on Page 2 of this form.

## Determine Area Z Angle

13. Return the load to the rear of the vehicle and extend the load to the Initial Testing Load Radius. Keep the load less than 4 " off of the ground.
14. Rotate the load clockwise. Monitor all vehicle tires to ensure they remain in contact with the test surface.
15. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
16. Use a protractor to determine this angle and write this angle on the Stability Test Results as Area Z.

## Determine Area W2 Length

17. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
18. Continue rotating the load clockwise while monitoring all vehicle tires.
19. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
20. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
21. Repeat this procedure until either the vehicle prevents further rotation or a 180 degree rotation of the load is reached.
22. Record the load radius in feet at this point on page 2 of this form as Area W2 Length.
23. Calculate the W2 \% Rated Capacity.
24. Write the $\boldsymbol{W} \mathbf{2}$ \% Rated Capacity in the Stability Test Results on Page 2 of this form.

## Record Stability Test Results on Placard

25. Record the information from the Stability Test Results on the CRANE TRUCK STABILITY plate (P.N. 18600) and install the plate in a visible position on the vehicle, preferably near the crane.

## THIS TEST IS NOW COMPLETE

## STABILITY TEST FORM

Operational limits of this vehicle


Determine the Testing Load Radius by using the following:


Area W1 Length $\qquad$
Testing Load Radius (ft.) $\qquad$
Multiply by 100 $\qquad$
W1 \% Rated Capacity $\qquad$

Area W2 Length $\qquad$
Testing Load Radius (ft.) $\qquad$
Multiply by 100 $\qquad$
W2 \% Rated Capacity $\qquad$
$180^{\circ}$

## STABILITY TEST RESULTS

| Area Y: | Degrees |
| :---: | :---: |
| Area Z: | Degrees |
| Area W1 Rated Capacity: | \% |
| Area W2 Rated Capacity: | \% |

$\qquad$ Date: $\qquad$

## CRANE SAFETY RULES

## CAUTION!

1. READ AND UNDERSTAND OPERATOR'S MANUAL.
2. INSPECT VEHICLE AND CRANE INCLUDING ITS OPERATION BEFORE DAILY USE.
3. USE THIS EQUIPMENT ONLY ON SOLID LEVEL GROUND WITH OUTRIGGERS OR JACKSTANDS PROPERLY SET.
4. BEFORE OPERATING THE CRANE REFER TO MAXIMUM LOAD CHART ON CRANE FOR OPERATING LOAD LIMITS.
5. BE SURE LOAD BEING LIFTED IS WITHIN SAFE WINCH CAPACITY AS WELL AS SAFE CRANE CAPACITY. MULTI-PART LINE OPERATION IS REQUIRED WHEN SINGLE LINE LOAD CAPACITY OF WINCH IS EXCEEDED.
6. DO NOT OPERATE, WALK, OR STAND UNDER THE BOOM OR ANY SUSPENDED LOAD.
7. ALWAYS PAY OUT LOAD LINE BEFORE EXTENDING BOOM. WIRE ROPE DAMAGE AND / OR BREAKAGE MAY OCCUR.
8. BOOM TIP MUST BE DIRECTLY OVER THE LOAD BEFORE ANY LIFTING IS STARTED. DO NOT DRAG LOADS WITH THIS CRANE.
9. BOOM MUST BE IN ITS BOOM REST BEFORE MOVING THE VEHICLE.
10. MAINTAIN THIS CRANE AS REQUIRED IN THE OWNER'S MANUAL.
11. DO NOT ALLOW PERSONNEL TO RIDE ON THE LOAD LINE, LOAD, OR BOOM OF THIS CRANE.
12. IT IS UNLAWFUL TO OPERATE THIS EQUIPMENT WITHIN TEN FEET OF HIGH VOLTAGE LINES.

## HFTMOORE

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## INTRODUCTION

This crane is a powerful machine designed to lift and move heavy loads. There are many hazards associated with these operations. Liftmoore has designed this crane to be as safe as possible but -

## IT IS THE OPERATOR'S RESPONSIBILITY TO PREVENT ACCIDENTS!

This takes pre-planning, attention, and knowledge of basic principles and rules. Even if you have used similar cranes, reading this manual in its entirety will help prevent damage, injury, or even loss of life; benefits well worth the short amount of time it takes to read these pages.

## REGULATORY AUTHORITY

Use of this crane is governed by OSHA 29 CFR 1910.180 and may be governed by other federal, state, or local regulations.

IT IS THE OPERATOR'S RESPONSIBILITY TO UNDERSTAND AND COMPLY WITH ALL APPLICABLE REGULATIONS GOVERNING THE OPERATION, INSPECTION, AND MAINTENANCE OF THIS CRANE.

Personnel should be trained, tested, and certified, as recommended by OSHA and ANSI standards, before operating this crane.

## USING THIS MANUAL

This manual assumes that the crane is mounted on a typical service body type or similar truck, which is powered by the vehicle electrical or hydraulic system, and is controlled by either the standard pendant control or FM radio control sold by Liftmoore, Inc.

This manual is supplied to provide basic guidelines for the safe use, routine maintenance, and general inspections of this crane.
This manual is supplied to provide basic guidelines for the safe use, routine maintenance, and general inspections of this crane.

Laws, regulations, standards, or policies may be more restrictive than this manual. If a conflict exists for any limit or condition, the safest or most prohibitive shall be used. Under no circumstances shall the load, moment, or stability ratings be exceeded.

Pay particular attention to the following:
WARNING! - Draws attention to hazards, conditions, or procedures that if not observed could result in injury or death.

CAUTION! - Draws attention to hazards, conditions, or procedures that if not observed could result in damage to the crane, load, or other equipment. Equipment failure could in turn lead to injury or death.

NOTE! - Draws attention to conditions or procedures that are essential to emphasize.

For questions, interpretations, or to report errors, please contact Liftmoore, Inc, Engineering Dept.

## OPERATING RESTRICTIONS

## DUTY CYCLE

For Electric Cranes the duty cycle time should be 5 minutes for every 30 minutes use cycle. This is recommended to increase lifespan of motors. This is limited by heat buildup in the motors and declining charge in the batteries. (Installing extra batteries near the crane helps keep the voltage at maximum.)

## PERSONNEL

LIFTING OR MOVING OF PERSONNEL IS STRICTLY PROHIBITED! This crane was neither designed nor intended to lift personnel. Under no circumstances should anyone be allowed to ride on the crane, line, or load. All non-essential personnel must be kept away when using the crane. The load must never be moved over people, nor must anyone be allowed to pass or stand under a suspended load.

## ELECTRICAL LINES

Consult ASME B30.5 for operating procedures, minimum safe distances, and prohibited zones when working around electrical lines or poles.

When operating near electrical power lines, the crane must be positioned so that the distance from the crane to the lines or poles is equal to or greater than the length of the fully extended boom plus the minimum safe distance required.

All parts of the crane, line, and load must be kept a minimum safe distance from electrical power lines and poles. This distance is 10 feet for electrical lines carrying 50 kV or less.

[^0]
## OPERATING PRACTICES


#### Abstract

SETUP POSITION The vehicle must be positioned so that the load is kept as close to the crane base as possible to reduce the moment on the crane. Consideration must be given to starting and ending position as well as firmness and slope of the ground and any obstructions.


OUTRIGGERS The outriggers or jackstands must be firmly set and the vehicle as level as possible. This will reduce the stresses on the rotation drive and keep the load off the vehicle's suspension. Keep in mind that the weight on the vehicle will shift as the crane and load is rotated.

## MANUAL BOOM EXTENSION If the

 manual extension part of the boom is needed, it must be extended and the boom pin placed in the required position. Insert the pin and replace the pin's hairpin keeper before attempting to lift any load.LOAD LIMIT The operator must understand the crane load chart. The operator must ensure that the load is within the load limits over the entire range which it will be moved. Be sure to include the weight of any lifting devices including the travel block.
The load limit chart is attached to the side of the crane to aid the operator.
The boom angle indicator and chart aids the operator in determining the load capacity at various boom angles and extensions. It also gives the load limit at that configuration.

STABILITY A stability chart must be posted near the crane. The operator must understand the stability chart. The crane may be de-rated over some areas of its operating radius.

TRAVEL BLOCK The operator must determine if the load is within the single line compatibility of the winch or if a multi-part line configuration is needed.

REEVING Ensure the proper routing of the rope through the sheaves and travel block. The rope must lie in the sheave groove and must not rub against any metal objects.

Ensure the rope is correctly wound on the winch drum. The crane assembly drawing will indicate if the rope must be wound over the top or bottom of the drum. The rope must never contact any part of the winch mounting.

## WARNING!

If the winch winding direction is reversed the brake will not work and the load will fall.

## ATTACHING THE LOAD

POSITION The boom tip must be moved over the load before lifting so that it will be lifted straight up.

## CAUTION!

Never drag a load with the crane. Dragging a load puts very high stresses on the crane for which it was not designed.

ROPE Check the rope condition to ensure it is not frayed or damaged. Ensure that the rope is not kinked and that it does not contact any sharp edges or make any sharp bends.

If using double line configuration, ensure that the lines are not twisted.

## CAUTION!

Never wrap the hoist rope around the load! Serious damage to the rope WILL occur.

HOOK Always make sure the load is applied to the throat of the hook. Never use a bent hook.

## CAUTION!

Always lift with the throat of the hook. Never lift with the load applied to the tip of the hook. Doing so will bend the hook.

SLINGS If the load does not have a lifting eye, use a nylon, chain, or other type of sling designed for lifting and rated for loads greater than that being lifted.

BALANCE Ensure the load will be secure and balanced when lifted. Ensure that the load cannot shift in the sling and that the sling cannot slide across the hook should the load become unbalanced.

## LIFTING THE LOAD

Before lifting, ensure that the load is free from all mountings and is no way attached or stuck to anything.

Ensure that at least five full wraps remain on the winch drum at all times.

Test the winch brake by lifting the load a few inches and ensuring that it does not slip.

## HOLDING THE LOAD

The operator must keep the load in sight at all times once it is lifted.

The operator must never leave the controls once the load is lifted.

The operator must ensure that no one is allowed to pass or stand under a suspended load.

## CAUTION!

Never move the vehicle with a suspended load. Doing so will put dynamic loads on the crane for which it was not designed.

## MOVING THE LOAD

Before moving the load, make sure the path is free of any obstructions or people.

Avoid sudden accelerations or stops. Speeds must be kept to a minimum, especially rotation, to keep the load from swinging.

Avoid sudden reversing of direction. Do not reverse direction while the load is still moving.

Make sure that no part of the crane, boom, or load makes contact with any obstruction or comes within a minimum of ten feet from any electrical line.

## TRANSIT

While in transit, the crane must be stowed, preferably in a boom rest. The crane must be prevented from rotating and the hook prevented from swinging.

## INSPECTION AND MAINTENANCE

OSHA and ASME require frequent and periodic inspections. Records of these inspections must be kept readily available. Liftmoore requires periodic maintenance to ensure proper operation and prolonged life of the crane.

## INSPECTION

## DAILY INSPECTION

OSHA 29CFR 1910.180 (d)(2)(i) requires the following be checked daily prior to use:

- All control mechanisms for maladjustment interfering with proper operation as well as for excessive wear of components and contamination by lubricants or other foreign matter.
- All safety devices for malfunction. This should include the anti-two block and pressure switch.
- Deterioration or leakage in air or hydraulic systems.
- Crane hooks with deformations or cracks. For hooks with cracks or having more than 15 percent in excess of normal throat opening or more than 10 deg. twist from the plane of the unbent hook.
- Electrical apparatus for malfunctioning, signs of excessive deterioration, dirt, and moisture accumulation. This should include the battery terminals, master disconnect switch, electrical swivel
- The wire rope shall be replaced if any of the following conditions are noted:
- Kinking, crushing, birdcaging, or other damage
- Reductions from nominal diameter of more than one-sixty-fourth inch for diameters up to and including five-sixteenths inch, one-thirty-second inch for diameters three-eighths inch to and including onehalf inch.
- Thimble is not in place or is damaged
- Any evidence of heat damage
- Six or more randomly distributed broken wires in 1 lay
- Three or more broken wires in 1 strand in 1 lay


## MONTHLY INSPECTION

A thorough inspection of all ropes in use shall be made at least once a month and a certification record which includes the date of inspection, the signature of the person who performed the inspection and an identifier for the ropes shall be prepared and kept on file where readily available. All inspections shall be performed by an appointed or authorized person. Any deterioration, resulting in appreciable loss of original strength shall be carefully observed and determination made as to whether further use of the rope would constitute a safety hazard. Some of the conditions that could result in an appreciable loss of strength are the following:

- Reduction of rope diameter below nominal diameter due to loss of core support, internal or external corrosion, or wear of outside wires.
- A number of broken outside wires and the degree of distribution of concentration of such broken wires.
- Worn outside wires.
- Corroded or broken wires at end connections.
- Corroded, cracked, bent, worn, or improperly applied end connections.
- Severe kinking, crushing, cutting, or unstranding.


## PERIODIC INSPECTION

An Annual Inspection Form is included in this manual. OSHA 29CFR 1910.180 (d)(2)ii) requires periodic inspections of this crane. Liftmoore recommends an annual inspection using the included form.

## MAINTENANCE PRECAUTIONS

The crane should be maintained monthly for safety reasons and to reduce stress on the crane.

## WARNING!

Never perform any maintenance while the crane has any type of load on it. Use the manual operation procedure to lower the load if necessary.

## WARNING!

Hydraulic cylinders may have high pressure stored in them even after hydraulic power is removed.

The counterbalance and pilot operated check valve in the cylinder will always hold some pressure in the cylinder. Slightly extending the cylinder then retracting a small amount will relieve most of the pressure in the cylinder. DO NOT DEADHEAD THE CYLINDER! This will store the maximum amount of pressure in the cylinder. Care should be taken when either valve is removed from the cylinder as some pressure will still remain.

After any maintenance has been performed the crane shall not be operated until all guards have been reinstalled, all safety devices reactivated, and maintenance equipment removed.

LUBRICATION Refer to the crane specification section for the periodic maintenance schedule and type of lubrication required.

BOLTS Bolts may loosen over time due to vibration; therefore, they should be checked periodically. If bolts need to be replaced, make sure they are replaced with bolts of equal or greater strength. Check the periodic maintenance schedule (Crane Specification Section) for bolt specification and torque.

## NOTE!

Sheave and boom and cylinder pivot bolts are not standard bolts. The shank and thread length of these bolts have been modified so that they do not pivot on the threads. Consult the parts section of this manual for part numbers of these bolts.

## OTHER MAINTENANCE

Refer to parts drawings for any specific maintenance or adjustment procedures such as hydraulic winch brake, rotation drive gear set adjustment, Etc.

## MONTHLY INSPECTION REPORT

Crane Model No. $\qquad$

## Serial Number

$\qquad$

| Are Boom Hitch Pins and Keepers in place? | Yes | No |
| :---: | :---: | :---: |
| Wire Line Hook with Safety Latch Working? | Yes | No |
| Is Hook OK, (Not bent)? | Yes | No |
| Is Thimble on Wire Rope OK? | Yes | No |
| Is Traveling Block in use? | Yes | No |
| Is Wire Rope OK, not kinked or frayed? | Yes | No |
| Are all Boom Sections straight? | Yes | No |
| Are Sheave Bolts in place and tight? | Yes | No |
| Do all Sheaves rotate easily? | Yes | No |
| Are Mounting Bolts tight? | Yes | No |
| Is Anti Two-Block functioning properly? | Yes | No |
| Is Boom Angle Indicator in place and functioning and is Chart legible? | Yes | No |
| Are Cylinder Mounting Bolts secure? | Yes | No |
| Are Winch Mounting Bolts tight? | Yes | No |
| When stopped does winch drift less than 1.0 Inches? | Yes | No |
| Is Load Chart in place and easily read? | Yes | No |
| Are functions on Pendant operating correctly? | Yes | No |
| Is Hydraulic Reservoir full? | Yes | No |
| Is Outrigger straight and functioning? | Yes | No |

Any items checked 'No' must be repaired before using this crane.

OWNER
MODEL NUMBER SERIAL NUMBER

DATE $\qquad$

Check the following:
__Crane Mounting Bolts (Torque)
__ Winch mounting Bolts (Torque)
__Boom mounting bolts
__Cylinder mounting bolts
__Cracks on boom (Check when extended)
___Extension Pads not worn excessively
__Cracks on housing
__Weld cracks on boom
__ Weld cracks on housing
__Boom swing approximately one inch or less at boom tip when retracted
___Hydraulic leaks
__Hoses not chafed or cracked
Sheaves not cracked
__Boom Tip
Traveling Block
__Sheaves not worn excessively
__Boom Tip
___Traveling Block
__Sheaves rotate freely
__Boom Tip
___Traveling Block
___Load Chart in place and legible
__Boom angle chart in place and legible
_Labels in place (See manufacturer's chart)
___Crane Hook Throat Opening within 15\% of standard
_Crane Hook not bent more than 10 degrees from plane
Hook safety latch operating properly
_Booms pin(s) and Keeper(s) in place (Manual Extension Section)
$\qquad$ Wire Rope removed if the following occurs:
Six randomly distributed broken wires in one lay or three broken wires in one strand in one lay.

Wear of one-third the original diameter of outside individual wires.
Kinking, crushing, bird-caging or any other damage.
Evidence of heat damage.
Reduction from nominal diameter of more than one sixty-fourth inch for diameters to five-sixteenths diameter and one-thirty-second inch for diameters three-eighths to onehalf inch.
$\qquad$ Wire Line installed as manufacturer requires.
__Protective covers in place
__Grease crane as required
Check fluid level
___Winch
__Gearbox
__Reservoir

Control system for proper operation
___Winch Up and Down
__Boom Up and Down
Boom In and Out
_Rotation CW and CCW

Anti Two-Block (Required on Power Extendible Cranes) interrupts:
$\qquad$ Boom Down
$\qquad$ Boom Out
$\qquad$ Winch Up
__Boom Up stopped by Up Limit Switch
__O_Otrigger or jackstand operable
__Outrigger crushing decal in place
__Outrigger and Jackstand operates properly
__Boom rest in place and used
___Load Sensor trips when overloaded
__ Winch Down does not overrun when stopped
__Crane stability chart in place and visible.
I certify that I have performed the above tests and that any deficiencies were corrected and now comply as above.

Signed $\qquad$
Print Name $\qquad$
Company $\qquad$
Address $\qquad$
City $\qquad$ State $\qquad$

## STANDARD HAND SIGNALS FOR CONTROLLING CRANE OPERATIONS

| HOIST. With forearm vertical, forefinger pointing up, move hand in small horizontal circle. | LOWER. With arm extended down. ward, forefinger pointing down, move hand in small horizontal circle. | USE MAIN HOIST. Tap fist on head; then use regular signals. |
| :---: | :---: | :---: |
| USE WHIPLINE (Auxiliary Hoist). Tap elbow with one hand; then use regular signals. | RAISE BOOM. Arm extended, fingers closed, thumb pointing upward. | LOWER BOOM. Arm extended, fingers closed, thumb pointing downward. |




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# GUIDER RADIO/CAN REMOTE CONTROL SYSTEM 

## GUIDER REMOTE

## INDEX

DESCRIPTION ..... 3
OPERATION ..... 4
INDICATOR LEDs ..... 6
TRANSMITTER AND RECEIVER SYNCHRONIZATION ..... 6
TEACH BY CAN CABLE ..... 7
TEACH BY RF ..... 7
CLONING ..... 7
BATTERY CHARGING ..... 8
OUTPUTS ..... 9
INPUTS ..... 10
INSTALLATION ..... 10
BEFORE APPLYING POWER! ..... 11
SYSTEM TROUBLESHOOTING USING ON BOARD GATE: ..... 12
ACCESSING THE CONTROL PANEL ..... 12
DIAGNOSTICS ..... 13
CALIBRATION ..... 14
HISTOGRAM ..... 17
RECEIVER SOFTWARE UPDATE ..... 18
GATE CONFIGURATION ..... 19
GATE SOFTWARE UPDATE ..... 20
WIRING CRANE RECEIVER ..... 22
WIRING ENGINE RECEIVER ..... 23
ROUTINE MAINTENANCE ..... 24
MAINTENANCE PRECAUTIONS ..... 24
TROUBLESHOOTING ..... 25
TROUBLESHOOTING CHART ..... 26
ERROR CODES CRANE RECEIVER ..... 28
TRANSMITTER PICTORIAL ..... 32
CRANE RECEIVER PICTORIAL ..... 33

## GUIDER REMOTE

TILT, CHASSIS SENSOR PICTORIAL ..... 35
ROTATIONAL, BOOM SENSOR PICTORIAL ..... 36
PRESSURE SENSOR PICTORIAL ..... 37
SPECIFICATIONS ..... 38
INSTRUCTION TO THE USER ..... 39

## GUIDER REMOTE

## DESCRIPTION

The GUIDER REMOTE is a state of the art microprocessor based Radio Frequency (RF) control system. It will provide the operator the ability to wirelessly operate equipment. The operator is required to follow all OSHA www.osha.gov and other applicable safety standards when operating the equipment. Do not use high power radio devices in close proximity of this product.

The remote control system consists of: the radio transmitter, main receiver module, engine receiver module, and associated optional equipment such as wiring harnesses.

The transmitter is equipped with a trigger, twist to release E-stop
switch, and toggle switches for the various functions. It includes a port for wired control via the built-in Controller Area Network (CAN) system ${ }^{1}$. This unit runs on a 3.7 V rechargeable Li-Ion battery when in wireless mode. When in wired mode, the transmitter runs with power supplied by the CAN cable. This is useful if the battery power gets too low to operate the transmitter but continued operation is needed. The port is also used to charge the internal battery.

The system's radio receiver has both a proportional output and ON/OFF outputs to accommodate the functions available on the transmitter. All outputs are current-sourcing. It also includes a port for wired

[^1](CAN) and
RS-232
communication for system
diagnostics.

## OPERATION

Power must be applied to the receiver module for the system to work.

Releasing the E-STOP will turn on the transmitter. Pressing the E-STOP button will turn off the transmitter. Pressing the E-STOP will turn off all outputs as a safety feature. If the transmitter goes out of range for more than 2 seconds, all the momentary outputs will turn off as a safety feature, the e-stop output will turn off after 10 seconds.

To operate a proportional output, toggle the switch of the desired function and pull the trigger to the level desired.
*Please note that if the trigger is pulled before the function is selected, the proportional output will not work as a safety feature. Release the trigger and begin again in the proper sequence.

Once the Guider transmitter is on, the operating screen will be displayed. On the top left corner of the screen is transmitter battery display. Plug in the transmitter as soon as possible after seeing the battery symbol turn red. See BATTERY CHARGING below. The top middle of the screen shows the LINK status with the receiver (CAN, RF, or NO LINK), and the top right of the screen shows the system voltage. Load capacity and any errors (if present) are then shown below this when connected to the CRANE receiver. When connected to
the ENGINE receiver, the display will show RUNNING ENGINE FUNCTIONS.

## CONFIGURATION MENU

To navigate to the configuration menu turn the transmitter and receiver off. Press and hold the HORN button then turn on the transmitter. Keep holding the button for greater than 10 seconds until the menu is shown. There are the following options under the configuration menu: TEACH MODE, CLONE TX, SLEEP TIME, RESET TX, and EXIT. To select an option press the HORN button. To scroll down, use the AUX switch and to scroll up, use the RPM switch. To EXIT the configuration menu and go to the operating screen select EXIT.

## TEACH MODE

Select this option to put the transmitter into teach mode and synchronize the receiver and transmitter. See transmitter and receiver synchronization below for more information.

## SLEEP TIME

To save battery life, the transmitter will turn off after 60 minutes no buttons are pressed. The user must press and release the E-STOP at this point to restore transmitter operation. To change the sleep time, select this option and use the RPM and AUX switch to change the number of minutes the transmitter waits to go to sleep. Press the HORN button to save the selected sleep time and exit.

## RESET TX

Warning! If the transmitter is reset, the receiver will have to be re-synchronized to the transmitter for operation! To reset the transmitter select RESET TX then press any button.

CLONE TX

Warning! This feature can pose a safety hazard for operators if both transmitters are used simultaneously! Use with caution! Occasionally, it is desirable to have more than one transmitter work with a single receiver. This is accomplished by a process called cloning. See CLONING below for more information.

## INDICATOR LEDs

The receiver module can identify problems with the system in the form of an error code (red LED will be blinking). Check the decal on the receiver to diagnose system problems. Then, refer to the ERROR CODE CHART in this manual for explanation of the error codes. The green LED indicator will blink on the receiver during active operation. It will turn on solid when the Gate is connected to Wi-Fi.

## TRANSMITTER AND RECEIVER <br> SYNCHRONIZATION

Each radio remote system is designed to operate with a unique radio ID code and RF channel sequence. Each receiver is programmed to respond only to the transmitter with the correct ID code/RF channel

## GUIDER REMOTE

sequence for which it is set. This feature allows multiple systems to work in close proximity to one another without interference.

In the event that a transmitter becomes damaged and a new one is needed, the receiver can be reprogrammed to respond to the new transmitter. To teach the ID code to the receiver, use the following procedure. *Please note that if this procedure is interrupted before it has completed, the system may have intermittent operation:
For 3B2783A, Crane Receiver:

## TEACH BY CAN CABLE

1. Plug the CAN cable into the CAN port on both the receiver and transmitter and operate a function on the transmitter until the LEDs on the front panel go from steady to flashing for at least 5 seconds. The
units will be synchronized at this point

## TEACH BY RF

1. Turn the transmitter and both receivers off
2. On the transmitter, go to the configuration menu above then select TEACH MODE
3. Apply power to the receiver (engine or crane). The transmitter will display SUCCESFUL and go to operating screen
4. Teach complete

## CLONING

Warning! This feature can pose a safety hazard for operators if both transmitters are used simultaneously! Use with caution! Occasionally, it is desirable to have more than one

## GUIDER REMOTE

transmitter work with a single receiver. This is accomplished by a process called cloning. Cloning allows an additional transmitter (B) to have the same ID code as the original transmitter (A). If this feature is desired, use the following procedure:

1. Make sure transmitters and receivers are off
2. On transmitter A, go to the configuration menu above then select TEACH MODE
3. On transmitter B, go to the configuration menu above then select CLONE TX
4. Wait for a few seconds until the screen displays SUCCESFUL
5. Turn off both transmitters
6. Synchronize one of the transmitters to the receivers

If cloning feature has been
invoked and is no longer desired, the ID code of one of the transmitters needs to be changed. This will unclone the transmitters. If this is desired, use the following procedure:

1. Make sure the receiver and transmitters are OFF
2. On the transmitter, go to the configuration menu above then select RESET TX
3. Press any switch again to select a new ID
4. Uncloning complete
5. Use transmitter and receiver synchronization procedure above to link the uncloned transmitter to new receivers

## BATTERY CHARGING

The transmitter is designed with a smart battery charger. The battery can be charged by
connecting the CAN cable from the receiver module (powered on) to the port on the transmitter, or by plugging the AC wall charger or DC cigarette charger (minimum 2A @ 12.6VDC) into the port. Red and green LED indicators on the underside of the transmitter indicate the status of the charger: A red LED indicates that the battery is charging and a green LED indicates that the battery is fully charged.

IMPORTANT BATTERY INFO
When the battery is new, the run-time of the transmitter will be shorter until it has gone through the drain/charge cycle several times. After this point, the unit's current drain should allow at least 20 hours of runtime before a recharge is needed.

The temperature that the transmitter battery is exposed to affects performance and useful life. It is strongly recommended you keep within the following limits:
A. Charging: -4 to $+86^{\circ} \mathrm{F}$
B. Operating: -20 to $+122^{\circ} \mathrm{F}$
C. Storing: -4 to $+86^{\circ} \mathrm{F}$ (lower is better)

## OUTPUTS

Each of the outputs from the receiver module is designed with built-in short circuit and overload protection. The outputs can also detect a noload or broken wire condition.

These error conditions are evident by the alphanumeric display on the receiver module or the HISTOGRAM page on the optional Gate.

The ON/OFF outputs will indicate an error under no load or broken wire status if NOT activated, and will detect a short IF activated. The proportional outputs will detect a no-load or short condition WHEN activated.

## INPUTS

Digital inputs are available for ATB, BOOM LIMIT, and PRESSURE signals. They will function up to battery voltage levels. One analog input is available for a PRESSURE TRANSDUCER. This expects a signal from 4-20mA.

## INSTALLATION

Refer to the WIRING CHART in this manual for hookup of the harness.

To install the receiver module, use the two mounting holes
provided on the enclosure to attach it in a vertical manner with the connectors facing down. Please take extra caution not to damage internal components while installing. For high vibration applications, use shock absorbing mounts. It is advised to mount the unit as high as possible, keeping clear of metal obstructions around the antenna which might affect RF performance. Antenna extension cables are available from KarTech to aid in this, if needed.

The main power to the receiver should be connected through a switched, fused line capable of a minimum of 20 amps. For best results, connect power (+) to the receiver via an auxiliary terminal of the ignition switch, PTO switch, or ignition relay. Be sure that the ground (-) is connected securely to the

## GUIDER REMOTE

chassis or battery with a star washer which digs into the base metal to insure good contact.

All connections must be properly insulated to protect against shorts.

Seal all connections with a nonconductive silicone grease to prevent corrosion.

## BEFORE APPLYING POWER!

- Check power and ground for proper polarity.
- Check the wiring harness for possible shorts before connecting to output devices (i.e., valves and relays) by checking each mating pin terminal.
- Verify that the transmitter battery is fully charged.
- Read the rest of this manual.


## GUIDER REMOTE

## SYSTEM <br> TROUBLESHOOTING USING ON BOARD GATE:

The GATE creates a $\mathrm{Wi}-\mathrm{Fi}$ access point which allows you to connect to any device with $\mathrm{Wi}-\mathrm{Fi}$ and web browser such as smart phones, pads or personal computers. It supports Google Chrome, Internet Explorer, Firefox and IOS Safari and allows user to configure, diagnose and troubleshoot the system.

## ACCESSING THE CONTROL PANEL

1. Turn on the power to the receiver.
2. Use your device and look for the available WiFi networks. A network under the name of "LIFTMOOREXXXXXXXXXX" should be available at
this point.The " $\mathrm{XXXXXXXXXX"} \mathrm{should}$ be the 10 digit numeric serial \# on the crane WIFI receiver. Connect to the network, if required password is 3B2785A1.
3. Once the connection is established, open a web browser on your device. The Chrome browser is recommended.
4. Enter the address http://192.168.1.1 in the address bar


Address Bar
5. If the Gate is not used for 5 minutes after power up it will automatically turn off. Recycle power to the receiver to turn it back on.
6. The following options are available from the main screen.

## GUIDER REMOTE



Main Screen

## DIAGNOSTICS

Tap the Diagnostic button to see the diagnostic screens, which shows the present state of remote communications, and system I/O.

When the round circle next to a label is dark, the corresponding ON/OFF input or output is sensed to be active or ON.


Diagnostics

## GUIDER REMOTE

## CALIBRATION

To change the configuration of the unit, tap the Calibration icon.


End user Calibration
Page Password $=1713$

## GUIDER REMOTE

## HISTOGRAM

Tap the Histogram icon to see a set of screens that show which error codes are active and how many times the specific error code has been active.

This feature can be used to troubleshoot machine wiring and other problems. Tapping the Reset button resets the error code counts. The password to reset error codes is (Contact Liftmoore Inc.). Tap the Home button to return to the main menu.

Note: the GATE is not a precision measurement instrument. There may be delays.


Histogram Page


Gate Configuration Page

## GATE CONFIGURATION

The password to gain access to the gate configuration page is (Contact Liftmoore Inc.).

This page allows you to change the name (SSID) of the Wi-Fi network you are connecting to. Factory settings will rename the $\mathrm{Wi}-\mathrm{Fi}$ to its original name.

If Broadcast SSID option is
selected, the $\mathrm{Wi}-\mathrm{Fi}$ name (SSID) is public and it will be visible to any other $\mathrm{Wi}-\mathrm{Fi}$ devices. Otherwise, the $\mathrm{Wi}-\mathrm{Fi}$ name (SSID) is hidden and it would require manual connection to the network.

If Enable Multiple Connections is selected, multiple connections up to 4 devices could be connected to the GATE. However, only one of the connected devices can use the GATE. If Single connection is enabled, only one device can be connected to the GATE.
NOTE: A reconnect to the new $\mathrm{Wi}-\mathrm{Fi}$ connection is needed after each change. It is advised to keep a note of the Wi-Fi name in case if Not Broadcast SSID option is selected. Forgetting the $\mathrm{Wi}-\mathrm{Fi}$ name after selecting this to be sent to KAR-TECH for RESET.

## GUIDER REMOTE

## WIRING CRANE RECEIVER

P1-DEUTSCH DTM13-12PA, GRAY

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | GROUND |
| 2 | CANH |
| 3 | CANL |
| 4 | N/C |
| 5 | N/C |
| 6 | BOOM PRESSURE 4-20mA INPUT |
| 7 | ANTI-TWO-BLOCK SWITCH INPUT |
| 8 | N/C |
| 9 | N/C |
| 10 | PROPORTIONAL SPEED CONTROL OUTPUT |
| 11 | HORN OUTPUT |
| 12 | POWER $(9-30 V)$ |

P2 - DEUTSCH DTM13-12PB, BLACK

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | ROTATION CW OUTPUT |
| 2 | ROTATION CCW OUTPUT |
| 3 | EXTEND OUT OUTPUT |
| 4 | EXTEND IN OUTPUT |
| 5 | BOOM UP OUTPUT |
| 6 | BOOM DOWN OUTPUT |
| 7 | HOIST UP OUTPUT |
| 8 | HOIST DOWN OUTPUT |
| 9 | N/C |
| 10 | E-STOP OUTPUT |
| 11 | N/C |
| 12 | BOOM UP LIMIT SWITCH INPUT |

## WIRING ENGINE RECEIVER

DEUTSCH DTM13-12PA

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | GROUND |
| 2 | $\mathrm{~N} / \mathrm{C}$ |
| 3 | $\mathrm{~N} / \mathrm{C}$ |
| 4 | $\mathrm{~N} / \mathrm{C}$ |
| 5 | ENGINE SPEED SELECT DIGITAL INPUT |
| 6 | $\mathrm{~N} / \mathrm{C}$ |
| 7 | $\mathrm{~N} / \mathrm{C}$ |
| 8 | AUXILIARY OUTPUT |
| 9 | ENGINE START OUTPUT |
| 10 | ENGINE STOP OUTPUT |
| 11 | ENGINE SPEED OUTPUT |
| 12 | POWER (9-3OV) |

## TRANSMITTER PORT

A POWER
B GROUND
C CAN HIGH
D CAN LOW
E NO CONNECTION
WIRING TILT AND ROTATIONAL SENSOR

| DT04-4P-E008 CON/ KT PN: 055-157-0402 |  |
| :---: | :---: |
| PIN | DESCRIPTION |
| 1 | POWER 9-30V |
| 2 | GROUND |
| 3 | CAN HIGH |
| 4 | CAN LOW |

## GUIDER REMOTE

ROUTINE MAINTENANCE
Clean transmitter regularly with a damp cloth and mild detergent.

Inspect electrical wiring for wear points or other damage. Repair as required.

Inspect all connections for looseness or corrosion. Tighten and/or "seal" as necessary.

Guider pendants that include a trigger control should be cleaned periodically by blowing air around the trigger area to remove any debris that would prevent proper operation. Apply a light machine oil to the point of rotation when clean.

## MAINTENANCE PRECAUTIONS

When performing any inspection
or maintenance work on the remote system, always exercise care to prevent injury to yourself and others or damage to the equipment. The following are general precautions, which should be closely followed in carrying out any maintenance work.

Do not have hydraulic power available to the valves when performing electrical tests.

Never operate or test any function if any person is in an area where they could be hurt by being hit or squeezed by the hydraulic equipment.

Turn power off before connecting or disconnecting valve coils or other electrical loads.

## GUIDER REMOTE

## TROUBLESHOOTING

This next section provides basic operator level troubleshooting for the GUIDER REMOTE system. If, after following these instructions, the system still does not function, contact your sales representative for further instructions or servicing.

## GUIDER REMOTE

## TROUBLESHOOTING CHART

| PROBLEM | SOLUTION |
| :--- | :--- |
| No functions work | $\begin{array}{l}\text { 1. Verify transmitter power source - battery, } \\ \text { CAN cable, external supply, etc } \\ \text { 2. Verify that receiver control module power } \\ \text { source is present at its input connector } \\ \text { 3. Check for proper system ground }\end{array}$ |
|  | $\begin{array}{l}\text { 4. Check the receiver or control module LED } \\ \text { status display for functionality or errors }\end{array}$ |
| 3. Check the hydraulic system |  |
| 4. Check to see if the crane receiver has |  |
| sufficient cooling. |  |\(\left.| \begin{array}{ll}1. Check the wiring and connections from <br>

the receiver control module to the control <br>
module to the valve coil for the particular <br>

function that does not work\end{array}\right\}\)| 2. Check the receiver control module LED |
| :--- |
| status display for possible fault or error |
| indication functions do not |
| work |$\quad$| 3. Check the hydraulic system |
| :--- |
| 4. Check the electrical system |

## GUIDER REMOTE

|  | and possible obstructions <br> 1. Check the hydraulic system |
| :--- | :--- |
|  | 2. Check to see if the crane receiver has <br> sufficient cooling. |

## GUIDER REMOTE

## ERROR CODES CRANE RECEIVER

| Receiver Display | Error Code | Transmitter Display |
| :---: | :---: | :---: |
| NOLK | RF Communication Error | RF signal will show red $x$ |
| WiFi | WiFi Linked to Device | N/A |
| RLV | Low Truck Battery Error | Truck low batt err |
| ESTP | E-STOP Condition | E-STOP mode err |
| XDCR | Transducer Error | Transducer err |
| OVLD | Overload Condition | Overload err |
| ATB | ANTI-TWO-BLOCK Condition | ANTI-TWO-BLOCK |
| BLMT | BOOM UP LIMIT Condition | Boom limit err |
| BSNS | BOOM (Rotate) Sensor Error | Boom angle sens err |
| CSNS | CHASSIS (Tilt) Sensor Error | Tilt sensor err |
| EC01 | ROTATE CW Output Error | Rotate CW err |
| EC02 | ROTATE CCW Output Error | Rotate CCW err |
| EC03 | EXTEND OUT Output Error | Extend out err |
| EC04 | EXTEND IN Output Error | Extend in err |
| EC05 | BOOM UP Output Error | Boom up err |
| EC06 | BOOM DOWN Output Error | Boom down err |
| EC07 | HOIST UP Output Error | Hoist up err |
| EC08 | HOIST DOWN Output Error | Hoist down err |
| EC09 | E-STOP Output Error | E-STOP out err |
| EC10 | HORN Output Error | Horn err |
| EC11 | SPEED Output Error | Speed out err |
| EC12 | TRIGGER Input Error | Trigger err |
| EC13 | TRIGGER before Switch Error | Trigger start err |
| N/A | N/A | Chassis tilted |

## Error code explanations: <br> NOLK Transmitter is off

Transmitter went to sleep mode
Interference in RF communication link
RLV System voltage is below 11V (12V system)
ESTP E-STOP button is pressed on the transmitter

## GUIDER REMOTE

XDCR No voltage present at pressure input or voltage is out of specified range ( $4-20 \mathrm{~mA}$ )

OVLD Overload condition based on Gate setting is present
ATB Anti-Two Block condition present, ATB input is low
BLMT Boom Limit input active, BOOM LIMIT input is low
CSNS No CAN messages are being received from Tilt sensor. Check wiring

BSNS No CAN messages are being received from Rotational sensor. Check wiring

EC1-10 Short or open load/coil on output
EC11 Current at SPEED output is above rated current, output will turn off

EC12 No voltage present on trigger in transmitter
EC13 Trigger was pulled on transmitter before switch was activated

Chassis tilted - If the chassis is tilted over five degrees, all functions are reduced to slow speed. The following outputs will also be disabled: Boom Down, Hoist Up, and Extend Out.

## ERROR CODES ENGINE RECEIVER

| EC | POSSIBLE CAUSE |
| :---: | :--- |
| 1 | RF COMMUNICATION ERROR |
| 2 | ENGINE SPEED OUTPUT ERROR |

## Error code explanations:

1 Transmitter is off
Transmitter went to sleep mode
Interference in RF communication link
2
Short or open load/coil on output

## PARTS LIST

| PART NUMBER | DESCRIPTION |
| :--- | :--- |
| $\mathbf{2 8 7 9 0}$ | RADIO TRANSMITTER |
| $\mathbf{2 8 7 9 2}$ | CRANE RADIO RECEIVER |
| $\mathbf{2 8 7 9 3}$ | ENGINE RADIO RECEIVER |
| $\mathbf{2 8 7 9 6}$ | CAN ADAPTOR CABLE 25' |
| $\mathbf{2 8 7 9 4}$ | SENSOR, PRESSURE,5K PSI, 4-20, 1/4-18 <br> NPT, DT04-3P |
| $\mathbf{2 0 1 8 6}$ | CHARGER, 12 VDC CIGARETTE LIGHTER PLUG |
| $\mathbf{2 4 5 1 0}$ | FAST CHARGER SUPPLY, 110V AC WALL |
| $\mathbf{2 8 7 9 5}$ | TILT SENSOR |
| $\mathbf{2 8 8 5 3}$ | ROTATIONAL SENSOR |

There are no user-serviceable parts inside the transmitter or the receiver. Return the units for service.

Note: For operation with negative ground systems only.

## WARNING:

The GUIDER REMOTE must be operated in compliance with all applicable safety regulations, rules, and practices. Failure to follow required safety practices may result in death or serious injury.

The information, specifications, and illustrations in this manual are those in effect at the time of printing. We reserve the right to change specifications or design at any time without notice.

## GUI DER REMOTE

## TRANSMI TTER PI CTORI AL



ERROR CODES).


## GUIDER REMOTE

## CRANE RECEIVER PICTORIAL


$\varnothing 0.29$ THRU 2PL FOR 1/4" OR 6mm FASTENER


## GUIDER REMOTE

ENGINE RECEIVER PICTORIAL


## GUIDER REMOTE

## TILT, CHASSIS SENSOR PICTORIAL



## GUIDER REMOTE

## ROTATIONAL, BOOM SENSOR PICTORIAL



## GUIDER REMOTE

## PRESSURE SENSOR PICTORIAL



| Parameter |  |
| :---: | :---: |
| Pressure Range | $0^{\sim} 5000 \mathrm{psi}$ |
| Pressure Connection Type | NPT1/4 |
| Electrical Connection | DT04-3P |
| Supply Voltage | $10^{\sim 36 V D C}$ |
| Output Signal | $4^{\sim} 20 \mathrm{~mA}$ |
| Accuracy | $\pm 0.5 \% \mathrm{~F} . S$ |
| Pressure cycle | $>10^{8}$ |
| Overload Pressure | 2 X |
| Burst Pressure | 10 X |
| Long-term stability | $\pm 0.25 \mathrm{~F}$. S/Year |
| Working Temperature | $-40^{\sim} 125 ?$ |
| Ingress protection | IP65 |

## GUIDER REMOTE

## SPECIFICATIONS

FCC ID: P4U-MOD164<br>Industry Canada Certification Number: 4534A-MOD164<br>EQUIPMENT CLASS: PART 15 SPREAD SPECTRUM TRANSMITTER

## TRANSMITTER

Power supply3.7V Li-Ion Rechargeable BatteryFast charger temperature range $+5^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$
Operating temperature - Radio ..... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage temperature ..... $-40^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
RF Frequency ..... 902-928 MHz
RF Transmit power (EIRP) ..... 100 mW
LCD display operating range (if equipped) ..... $-20^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Vibration ..... 3G to 200 Hz
Shock ..... 50G
NEMA ..... 12
RECEIVER
Power supply voltage ..... 9-30VDC
Operating temperature ..... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage temperature ..... $-40^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Outputs 5.0A max each, sourcing, 20A system max
Digital Inputs (when equipped) ..... supply voltage
Analog Inputs (when equipped) ..... 0-5VDC/4-20mA
RF Frequency ..... 902-928 MHz
Vibration ..... 3G to 200 Hz
Shock ..... 100G
NEMA ..... 4X

## GUIDER REMOTE

## INSTRUCTION TO THE USER

This equipment has been tested and found to comply with the limits for a class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates radio frequency energy and if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

* Reorient or relocate the receiving antenna.
* Increase the separation between the equipment and receiver.
* Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
* Consult the dealer or an experienced radio/TV technician for help.

This equipment has been certified to comply with the limits for a class B computing device, pursuant to FCC Rules. In order to maintain compliance with FCC regulations, shielded cables must be used with this equipment. Operation with non-approved equipment or unshielded cables is likely to result in interference to radio and TV reception. The user is cautioned that changes and modifications made to the equipment without the approval of manufacturer could void the user's authority to operate this equipment.

To make sure receiver has latest updates hook up to your crane WIFI. Once in the home page select "DIAGNOSTICS" and scroll down to the bottom of the screen and you should see the dates listed below. If you do not see these dates, contact Liftmoore Cranes (see contact info below).

## Receiver Software: 3Z8349DX Date: 11/02/22

## Gate Software: <br> 3Z834ADX Date: 11/28/22

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IFTMOORE

## SAFETY SYSTEM

The safety system is designed to help prevent damage to the crane that would be caused by overload or two-blocking. The system consists of a load sensor, anti-two block device (optional on smaller, electric cranes), and limiting system control board.

When the applicable switch detects an overload or two-block condition, the limiting system will prevent activation of winch up, boom down, and extend out since these directions would cause damage. Winch down, boom up, extend in, and power rotation will still function so that the crane can be moved to a safe configuration.

## CAUTION!

Never de-activate or override safety functions. Doing so can result in serious damage to the crane and possibly injury or death.

## OVERLOAD PROTECTION

A pressure activated switch in the elevation cylinder acts as a load sensor. This switch is normally closed and opens at the preset pressure corresponding to the load rating of the crane.

## CAUTION!

The load sensor will not function when the elevation cylinder is fully retracted and is inaccurate when the boom is below horizontal.

## CAUTION!

The operator must never rely strictly on the load sensor to determine overload conditions. The load and load limits must always be known and adhered to.

## ANTI-TWO BLOCK

The anti-two block device (optional on smaller electric cranes), mounted on the boom crown plate, consists of a normally open switch actuated by a lever. A pickle weight or bail arms are attached to the lever
and holds the switch closed. If the pickle weight or the bail arms are lifted by the hook or travel block the switch opens.

The power and signal wires are wired through the cord reel, which is in turn wired to the ATB switch.

## LIMITING SYSTEM CONTROL

The limiting system control prevents output of winch up, boom down and extend out if it is not receiving a signal from either the ATB or load sensor.

The ATB does not trip boom down when winch is mounted on the boom.

There is a one second delay before deactivation of boom down when the load sensor is tripped to prevent false readings caused by pressure spikes.

## MISCELLANEOUS

## UP LIMIT SWITCH

The up limit switch prevents the elevation cylinder from reaching full extension. If the elevation cylinder were to "dead-head", the resulting pressure would activate the load sensor, preventing boom down. The boom would then have to be lowered using the manual operation buttons on the solenoid valves.

## CIRCUIT BREAKER, FUSE

For electric cranes a 150 Amp circuit breaker is supplied with the crane. It should be installed as close to the battery as possible. For hydraulic cranes a 30 Amp blade type fuse is supplied.

## DISCONNECT SWITCH

A power disconnect switch is supplied with the crane. Power to the crane should be turned off whenever not in use. This is to prevent inadvertent or unauthorized use and will help prevent corrosion at electrical connections.

## HYDRAULIC SYSTEM

Hyd Proportional
The hydraulic system consists of the hydraulic swivel, manifold with solenoid valves, cylinders, motors, and tubing and hoses. Hydraulic power is received from an external hydraulic source, typically a PTO driven pump attached to the vehicle transmission. The hydraulic system uses open center valves in series so that multiple functions can be operated simultaneously.

## SWIVEL

The hydraulic swivel is a two-port swivel that allows continuous, unlimited rotation. Refer to drawing for more information.

## MANIFOLD

The hydraulic manifold consists of a differential pressure sensing flow control valve, the system relief valve, proportional flow control valve, and 4 way directional control valves.

The Logic valve is a pilot operated pressure compensated flow control cartridge valve. It supplies the required flow to the manifold and returns excess flow to the tank so that pressure drop and heat build up are minimized.

The system relief valve prevents damage that would be caused by excessive pressure in the system. It is a cartridge type valve.

Factory relief valve settings per model.
8045-22/30 2800 PSI
60100-24/30 2900 PSI
72100-24/30 2900 PSI
The proportional valve is an electrically operated flow control valve. It allows the operator to control the flow, and therefore the speed, of the selected functions. The flow output is directly proportional to the electrical input. The valve may be operated manually by depressing the manual operation button on the top of the valve.

Each hydraulically operated function is controlled by a 4 way, 3 position open center solenoid valve. It is electrically operated and spring biased to center. A manual operation button is incorporated in the coil retaining nut.
Each hydraulically operated function is controlled by a 4 way, 3 position open center solenoid valve. It is electrically operated and spring biased to center. A manual operation button is incorporated in the coil retaining nut.

## CYLINDERS

Hydraulic cylinders are double acting cylinders with integrally mounted counterbalance valve and pilot operated check valves. Refer to the cylinder drawings for specific information.

All cylinders use a counter-balance load holding cartridge valve on the extend port. This valve performs 3 functions:

- Controls the rate of decent when lowering the load
- Keeps load from falling in the event of sudden loss of system pressure, such as when a hose bursts.
- Acts as a relief valve to prevent damage from induced load or thermal expansion.

It allows free flow to extend then blocks flow until opened by pilot pressure to the retract port or when the relief pressure is reached.

Some cylinders utilize a pilot operated check valve on the retract port to prevent the cylinder from creeping out under no load conditions. This valve allows flow into, but prevents flow from the retract port, thus hydraulically locking the cylinder until opened by pilot pressure to the extend port.

## MOTORS

The hydraulic motors used by the rotation drive and hydraulic hoist are high torque, low speed constant displacement motor.

## MANUAL OPERATION

If electrical problems occur the solenoid valves may be operated manually. Refer to the electrical schematic drawing for function valves and directions.

## MANUAL OVERRIDE ELEVATION, EXTENSION, ROTATION

First override the Proportional valve by turning the screw located on the valve clockwise. Turning the screw all the way in will result in overriding the valve at full speed if slower speed is desired turn screw counterclockwise to restrict flow.

Directional control valves are manually operated by depressing the boot at the end of the valve. Use a blunt object (e.g. bolt or screwdriver handle) to assist in the operation (Except hoist functions).

## MANUAL OVERRIDE HOIST

First override the Proportional valve by turning the screw located on the valve clockwise. Turning the screw all the way in will result in overriding the valve at full speed if slower speed is desired turn screw counterclockwise to restrict flow.

Then feed 12VDC to the purple wire going to the coil on the hoist valve (hoist valve is located on the hoist). Next locate the hoist directional control valve, operate the valve by depressing the boot at the end of the valve. Use a blunt object (e.g. bolt or screwdriver handle) to assist in the operation.

## LOWERING LOAD WITH COUNTER-BALANCE VALVE

If hydraulic power is lost while a load is suspended, the load may be lowered by decreasing the setting on the counterbalance valve. This should only be done in extreme cases. The valve must be reset before the crane is returned to use.

To decrease the setting, loosen the locknut on the valve, then slowly turn the adjustment stem CLOCKWISE until the load begins to lower. Count the number of turns so that the valve can be returned to its original setting.

Alternately, a pressure gage must be put on the retract port to adjust the setting so that approx. 1800 PSI is required to lower the boom with no load.

Test the setting by lifting a known load near the moment rating of the crane.

## BASIC TROUBLESHOOTING

The following chart gives a quick reference to help identify and correct problems. Refer to the following pages for more detailed information.

| PROBLEM | PROBABLE CAUSE | CORRECTIVE ACTION |
| :---: | :---: | :---: |
| NO FUNCTIONS WORK | Not receiving electrical power <br> Not receiving hydraulic power <br> Control problem | Check all connections Check all fuses and circuit breakers Check for electrical power at first electrical connection and trace back to crane <br> Check flow from pump Deadhead cylinder and check pressure at pump |
| FUNCTION NOT WORKING <br> winch up, extension out not working <br> Boom down, winch down, extension in not working <br> Other function not working | No signal from ATB or Load sensor (switch tripped, bad switch, bad wiring or not receiving power) <br> Relay card malfunction <br> Not receiving enough pressure <br> Faulty wiring <br> Valve coils bad | Check input signal to relay board if no signal, trace back to switch <br> Check LEDs on board for error codes and outputs <br> Deadhead cylinder and check pressure at pump <br> Check differential pressure valve for contamination <br> Check relief valve for proper setting and possible contamination <br> Check all wiring for breaks or shorts Check all ground wires for good connection <br> Check coil resistance |
| ALL FUNCTIONS SLOW <br> * These items only apply to cranes with proportional control systems. | Not receiving enough flow <br> Low battery voltage Check with engine running <br> * Proportional valve problem <br> * Control problem | Check fluid levels Check all filters and any other restrictions <br> Charge battery <br> (BATTERY MAY BE BAD) <br> Try manual operation of proportional valve <br> Check voltage at valve for approx. at min and max(see troubleshooting form for specific valves) <br> See control section |

## IFTMOORE

## TROUBLESHOOTING THE PROPORTIONAL SYSTEM

If no functions work or if all functions are slow when controlled by the pendant, but work correctly when the manual operation button is pressed on the proportional valve then the problem is with the proportional electronic control system.

## Proportional Valve Parameters

| Cracking voltage | 2.6 V |
| :--- | :--- |
| Full open voltage | 7.75 V |
| Coil Resistance | $3.66 \Omega$ |

CHECK VOLTAGE AT VALVE
Have the engine running to generate sufficient voltage ( $13-14 \mathrm{~V}$ ). As the trigger is pulled the valve voltage should start near zero, jump to the valve cracking voltage after slight trigger travel, increase steadily as the trigger is pulled, reaching the full open voltage.

If the voltages are correct, check the resistance across the coil. If the resistance differs significantly from the nominal resistance replace the coil.

## IFTMOORE

## DEUTSCH CONNECTIONS \& PINS



F2435-A
11/27/17
I:IFORMS

## SECTION V <br> CRANE SPECIFICATIONS MODEL 8045DX-30 CRANES

MOMENT RATING
MAX SINGLE LINE LOAD
MAX DOUBLE LINE LOAD

45,000 FT-LBS
4,000 LBS
8,000 LBS

LIFTING CAPACITIES AT VARIOUS LOAD RADII


POWERED FUNCTIONS AND EXPECTED TIMES

| WINCH | UP: | 3.3 s | DOWN: 3.8 s | 1 REVOLUTION |
| :--- | :--- | :--- | :--- | :--- |
| BOOM ELEVATION | UP: | 20 s | DOWN: 20 s |  |
| BOOM EXTENSION | OUT: | 41 s | IN: 33 s |  |
| ROTATION | $90^{\circ}$ | 15 s |  |  |

HYDRAULIC REQUIREMENTS

| PRESSURE | $2,800 \mathrm{PSI}$ |
| :--- | :--- |
| FLOW | 8 GPM |

ELECTRICAL REQUIREMENTS

| VOLTAGE | 12 VDC |
| :--- | :--- |
| FUSE | 15 AMP |

NOTE: FUNCTION TIMES ARE BASED ON THESE INPUT VALUES

## FG®®

HOUSTON, TEXAS

| PERIODIC MAINTENANCE SCHEDULE <br> MODEL 8045 CRANES |  |  |
| :---: | :---: | :---: |
| BOLTS |  |  |
| MOUNTING BOLTS | 7/8-9 GRADE 8 TORQUE 600FT-LBS DRY | EVERY 4 MONTHS |
| BEARING BOLTS <br> (REFER TO BASE-HOUSING ASSEMBLY) | 5/8-11 GRADE 8 TORQUE 170FT-LBS DRY | EVERY 4 MONTHS |
| LUBRICATION |  |  |
| GREASE FITTINGS | SEE DRAWING 50048 | EVERY OTHER WEEK |
| HYDRAULIC FLUID | STANDARD <br> Chevron AW Hydraulic Oil 46 or equivalent SAE 15 weight oil <br> COLD WEATHER <br> AW 32 or equivalent SAE 10 weight oil | CHECK DAILY, FILL AS NEEDED |
| WINCH GEARBOX | HLP ISO VG 46 | EVERY MONTH |
| ROTATION GEARBOX | EP 01 Grease | EVERY MONTH |
| BEARING <br> (ZERK AND TEETH) | Oil Center Research PM 600 Military grease or equivalent Benton Based Grease NLGI Grade 2 | EVERY 6 HOURS OF OPERATION |

## CRANE LUBRICATION POINTS



## LIST FOR BOX, CRANE PARTS 8045DX WP

> Items with * have detailed DWG's.

P/N 29689 - BOX, CRANE PARTS 8045DX-30

| 1) | P/N 29688 - MANUAL, CRANE 8045DX-30 WP. | pc |
| :---: | :---: | :---: |
| 2) | P/N 29884 - EWH, DUAL SWIVEL PWR WIRES. | 1 pc |
| 3) | P/N 16110 - TERMINAL, BUTT 10-12 GA. | 1 pc |
| 4) | P/N 15771 - TERMINAL, RING 10-12 GA 0.31 | 2pcs |
| 5) | P/N 18457 - FUSE, HOLDER, ATO 12 GA SEALED. | 1 pc |
| 6) | P/N 21154 - FUSE, 30AMP BLADE. | 1 pc |
| 7) | P/N 32613 - ADAPTER, 8MJ-10MJ. | 1 pc |
| 8) | P/N 17012 - SWITCH, TOGGLE SPST MAINT. /S. | 1 pc |
| 9) | P/N 17011 - BRACKET, SWITCH MNT. HYD. GRN | 1 pc |
| 10) | P/N 16781 - TERMINAL, RING 10-12 GA \#8 | 2pcs |
| 11) | P/N 17013 - PLATE, ON/OFF FOR TOGGLE SWCH. | 1 pc |
| 12) | P/N 18600 - PLATE, CRANE-TRUCK STABILITY CHART | .1pc |
| 13) | P/N 29574 - DECAL, LOAD CAPACITY 40,000. | 1 pc |
| 14) | P/N 23144 - LEVEL AND TAPE ASSEMBLY | .1pc |
| 15) | P/N 28836 - WIRE, GROUND \#6 X 60" W/TRM. | .1pc |
| 16) | P/N 30675 - COVER, TOGGLE SWITCH. | 1pc |
| 17) | P/N 70053 - NUT, TOGGLE SWITCH. | .1pc |
| 18) | P/N 70054 - WASHER, LOCK TOGGLE SWITCH | 1pc |
| 19) | P/N 70055 - SCREW, MH FH 6-32 X 0.25. | 2pcs |
| 20) | *P/N 29259 - BLOCK, TRAV ASSY 8.0K lbs/6.5D. | 1 pc |



## 6-3




## 6-5








6-11










## 6-21




| ITEM | PART NUMBER | DESCRIPTION | QTY |
| :---: | :---: | :--- | :---: |
| 1 | 19918 | CONTACT, DEUTSCH 12 GA FEMALE | 1 |
| 2 | 19919 | CONTACT, DEUTSCH 12 GA MALE | 2 |
| 3 | 29763 | CONNECTOR, DTCH 2P RECPT 12GA | 1 |
| 4 | 29764 | WEDGE, DEUTSCH 2P RECPT 12GA | 1 |
| 5 | 15576 | WIRE, ELECTRIC 10GA BLK | 10 |
| 6 | 26082 | WIRE, ELECTRIC 10GA RED | 10 |
| 7 | 19916 | CONNECTOR, DTCH IP PLUG | 1 |
| 8 | 15871 | TERMINAL, RING 14-16 GA 0.31 | 1 |










| CIRCUIT NUMBER AND DESCRIPTION |  |  |  |  |  |  | $\frac{0}{3}$ | エ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Color L | Length | Connectors |  | Function |  |  |  |  |
| RED | 23＂ | P12B． 1 | P2－R． 1 | ROT CW |  |  |  | ¢ |
| RED／BLK | 18＂ | P12B． 2 | P2－RA． 1 | ROT CCW |  |  | 入 | － |
| GRN | 23＂ | P12B． 5 | P2－L． 1 | BOOM UP |  |  | ¢ | N |
| ORN | 18＂ | P12B． 6 | P2－LA． 1 | BOOM DWN |  | İ | ¢ |  |
| GRN／BLK | 19＂ | P12B． 3 | P2－X． 1 | EXT OUT |  |  | ¢ |  |
| ORN／BLK | 25＂ | P12B． 4 | P2－XA． 1 | EXT IN |  | $\triangle$ | \％${ }^{\text {c }}$ |  |
| BLU BLK | $\begin{aligned} & 28 " 1 \\ & 26 " \end{aligned}$ | $\begin{aligned} & \text { P12B. } 7 \\ & \text { P12B. } 8 \end{aligned}$ | $\begin{aligned} & \text { P2-HA. } 1 \\ & \text { P2-H. } 1 \end{aligned}$ | HOIST UP <br> HOIST DWN |  |  |  | 끈 |
| WHT／BLU | 15 | P12B． 10 | P2－RES． 1 | E－STOP |  |  | 圣宸 | ㄱ |
| WHT | 15＂ | P12B． 12 | P2－U． 2 | UP LIMIT SWITCH |  |  | $\bigcirc$ |  |
| RED | 19＂ | P12D． 8 | P2－U． 1 | UP LIMIT SW．12V |  |  | $\bigcirc$ | 름 ${ }^{\text {a }}$ |
| WHT／BLK | 26＂ | P12A． 10 | P2－P． 1 | PROP |  |  | 핀 |  |
| WHT | 13＂ | P12A． 2 | P4－CH． 1 | CAN HI MAIN |  |  |  |  |
| GRN | 13 ＂ | P12A． 3 | P4－CL． 1 | CAN LOW MAIN |  |  |  |  |
| YEL／BLK | 13＂ | P12A． 7 | P2－ATB． 2 | ATB |  |  |  |  |
| RED | 20＂ | P12A． 12 | P12D． 2 | REC．PWR 12V |  |  | 융ㅇ |  |
| RED | 17＂ | P12D． 3 | P2－ATB． 1 | PWR，ATB 12V |  |  | H | 岩 |
|  |  |  |  |  |  | 令 | 䍗落。 | 合 |
| RED | 16＂ | P12D． 4 | P4－J． 1 | PWR，CAN 12V |  |  |  | 궁앙 |
| GRN | $9{ }^{\prime}$ | P4－CL． 2 | P4－J． 3 | CAN LOW |  |  |  |  |
| WHT | $9{ }^{\prime \prime}$ | P4－CH． 2 | P4－J． 4 | CAN HI |  |  |  | 岂 |
| YEL | N／A | P12D． 1 | MAIN PWR | F FUSE HOLDER |  |  |  |  |
| BLK | $16 "$ | P12A． 11 | 1 BLU／FEM | HORN 12V |  |  |  |  |
| PUR | 46＂ | P12B． 9 | P2－WV． 1 | WINCH VALVE 12V |  |  |  |  |
|  |  | MAIN GRO | UND TERMI | INAL |  |  |  |  |
| BRN | 10＂ | P12C． 1 | TR－1 MA | AIN GROUND |  |  |  |  |
| BRN | 17＂ | P12C． 2 | P12A． 1 RE | ECEIVER GROUND |  |  |  |  |
| BRN | 19＂ | P12C． 3 | P2－RA． 2 RO | OOT CCW VALVE GND |  |  |  |  |
| BRN | 24＂ | P12C． 4 | P2－R． 2 RO | OOT CW VALVE GND |  |  |  |  |
| BRN | 24 | P12C． 5 | P2－L． 2 EL | LEV UP VALVE GND |  |  |  |  |
| BRN | 19＂ | P12C． 6 | P2－LA． 2 EL | LEV DWN VALVE GND |  |  |  |  |
| BRN | 20＂ | P12C． 7 | P2－X． 2 EX | XT OUT VALVE GND |  |  |  |  |
| BRN | 26＂ | P12C． 8 | P2－XA． 2 EX | XT IN VALVE GND | $\bigcirc$ | ${ }^{\underline{W}}$ |  | 兂 |
| BRN | 27＂ | P12C． 9 | P2－H． 2 WI | INCH DN VALVE GND | $\pm$ | 종 |  |  |
| BRN | 29＂ | P12C． 10 | P2－HA． 2 WI | IINCH UP VALVE GND |  | $\begin{aligned} & \text { T } \\ & \text { 응 } \end{aligned}$ |  | 篂 |
| BRN | 27＂ | P12C． 11 | P2－P2 PR | ROP．VALVE GND | $\cdots$ | $\begin{aligned} & \text { Ko } \\ & 0 \\ & 0 \end{aligned}$ |  | ${ }^{\circ}$ |
| BRN | 13＂ | P12C． 12 | P4－J． 2 CA | AN GND | 1 | $\begin{aligned} & \text { Do } \\ & \text { ox } \\ & \hline \end{aligned}$ |  |  |
|  |  | P6－GND GR | ROUND TER | RMINAL |  | 菟药 |  |  |
| BRN | 10＂ | P6－GND． 1 | TR－1 | MAIN GROUND | 0 | \％ |  |  |
| BRN | 33＂ | P6－GND． 5 | BF－1 | HORN GND |  |  |  |  |
| BRN | $16 "$ | P6－GND． 6 | P2－RES． 2 | RESISTOR GND |  |  |  |  |
| BRN | 50＂ | P2－WV． 2 | TR－1 | WINCH VALVE GND |  |  |  |  |





TRANSMITTER AND RECEIVER ARE PROGRAMMED TO FORM A MATCHED SET SO THAT A TRANSMITTER ONLY OPERATES ONE CRANE.

P/N 28790 CONTROL, FM TRANS GUIDER
NOT SHOWN ITEMS:
-P/N 28796 - WIRE, CTRL FM TETHER 25' CAN
P/N 20805 SCREW HHC 0.25-20 $\times 1.00$ SS
-P/N 28690 - WASHER, LOCK 0.25316 SS

- P/N 29405 - WASHER, FLAT 0.25 SS 316

OPTIONAL:
-P/N 24510 - CHARGER, FM TRANS AC GUIDER


## LIFTMOORE LIMITED WARRANTY

Parts and Structural

Liftmoore, Inc. warrants each LIFTMOORE crane to be free from defects in materials and workmanship for twelve (12) months from the date of delivery to the original customer. Under the terms of this warranty the crane structural components manufactured by LIFTMOORE, Inc. are warranted for thirty-six (36) months from the date of delivery to the original customer. LIFTMOORE, Inc. will repair or replace, as its sole discretion, any equipment or part that is returned f.o.b. to LIFTMOORE, Inc.'s plant at 7810 Pinemont Drive, Houston, Texas 77040, or to one of its authorized dealers, and is found by LIFTMOORE, Inc. or its authorized dealer to have been defective at the time of original delivery.

The foregoing warranty is the exclusive warranty made by LIFTMOORE, Inc. with respect to its cranes and is in lieu of all other warranties. ANY AND ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, INCLUDING ANY WARRANTY OF MERCHANTABILITY OR FITNESS OF ANY CRANE FOR A PARTICULAR PURPOSE OR OPERATION, ARE HERBY EXPRESSLY DISCLAIMED.

The foregoing warranty applies only to LIFTMOORE cranes under normal use and service and does not apply in the event of damage caused by repair or alteration or damage during shipment, accident, negligence, overloading, or misuse, including operator's failure to follow any of the instructions issued with the crane.

This warranty is limited to the original purchaser and is not assignable. In order to submit a claim, the original purchaser must provide a copy of the original invoice for the crane in question within twelve (12) months following the delivery date and within 30 days from the date of repair.

The warranty applies only when the LIFTMOORE crane is used for commercial purposes and does not cover any purchase for use for personal, family or household purposes.

LIMITATION OF LIABILITY: LIFTMOORE, Inc.'s liability for any losses or damages resulting from any cause whatsoever, including LIFTMOORE, Inc.'s NEGLIGENCE or from a defective crane irrespective of whether such defects are discoverable or latent, shall in no event exceed the purchase price of the crane to which losses or damages are claimed, or at the election of LIFTMOORE, Inc., the repair or replacement of the defective crane.

In no event shall LIFTMOORE, Inc. be liable for any special, incidental, or consequential damages, including commercial losses or costs of any kind sustained by purchaser or any other person or for any damages for which purchaser may be liable to other persons by reason of any defect in any LIFTMOORE crane or any part thereof.

LIFTMOORE, Inc. reserves the right to make changes in design or construction of its cranes at any time without obligating itself to make such changes on cranes previously manufactured.

No agent, employee, or representative of LIFTMOORE, Inc. has authority to amend or modify the foregoing warranty or to bind LIFTMOORE, Inc. by any other warranty, guaranty, or assumption of liability.

In the event any provision of this warranty is for any reason held ineffective, the remaining provisions shall remain in full force and effect.

Some states do not allow limitations on how long an implied warranty lasts or the exclusion or limitation of incidental or consequential damages, so the above limitations and exclusions may not apply to you. This warranty gives you specific legal rights, and you may also have other legal rights that vary from state to state.


[^0]:    UNDER NO CIRCUMSTANCES SHOULD A CRANE BE OPERATED UNDER ELECTRICAL POWER LINES.

[^1]:    ${ }^{1}$ The CAN control will only work with the CRANE module. The ENGINE module only works on RF

