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Read and understand this complete section before starting the crane installation.
Before installing make sure you have all necessary parts. Please refer to the Owner's manual Parts Section Box parts list for the list of parts required for installation. Report any shortages to Liftmoore, Inc. immediately.

1. The mounting surface for the crane must be capable of supporting the rated moment and maximum load of the crane as listed below:

$$
\begin{array}{ll}
5000-25,000 ~ F t .-L b s . ; ~ 5,000 ~ L b s . ~ \\
6036-36,000 ~ F t .-L b s . ; ~ 6,000 ~ L b s . ~
\end{array}
$$

2. Layout the mounting holes for the crane as shown in the drawing No. 31556 in this manual. Cut the center hole for the crane swivel as shown on the drawing. On cranes with auxiliary controls the rotation is restricted by a lever located on the base plate. Locate this rotation stop opposite the point where the boom will be restricted. Mount the crane with four 7/8" bolts of at least Grade 8 quality.
3. A manual disconnect switch with mounting bracket and terminals is provided with the crane. This switch will act as the main power disconnect for the crane. Removing power from the crane during periods of non-use will help to increase the life of the crane's electrical components. The switch should be mounted as near as possible to the crane and in a position which will facilitate its use. Determine the appropriate mounting position for the switch and use the supplied terminals to splice into the crane's main power cable. Drawing No. 50836 illustrates how to install the disconnect switch and circuit breaker.
4. To achieve the rated load of this crane a second battery needs to be installed in the vehicle as close as possible to the crane. This keeps the line loss (voltage drop) to a minimum and adds to the life of the crane's electrical components. Connect all batteries using the $1 / 0$ cable and make sure that each battery has the additional ground wire to the vehicle's frame.

The second battery near the crane should be a Group 4D or larger battery. Longer life of the battery will result if a "Deep Cycle" battery is installed. An example of this is a Douglas 12 V 215 sweeper battery. This battery has a 215 Amp-Hour rating and is commonly used in industrial sweepers.
5. Install the circuit breaker, which is supplied with the crane, near the battery on the positive line. This breaker is to protect the battery in event of an accidental grounding or shorting of the positive wire, (SEE DWG. 50836) for breaker installation. Use a section of the wire and the terminals supplied to connect between the battery and the circuit breaker. See drawing No. 50836.
6. Run the $1 / 0$ battery cable, which is provided with the crane, along the inside of the chassis frame to the positive battery terminal and connect it to the battery using a universal or marine type wing nut lug terminal. Make sure that the cable is protected avoiding sharp edges and heat sources such as the muffler or catalytic converter. Use loom for protection whenever the cable passes through the body.

## MODEL 5000\＆ 6036 INSTALLATION INSTRUCTIONS，Cont．

7．Run the extra ground wire supplied from the negative battery terminal to the truck＇s main frame．Leave the regular ground to the engine as is．The end of both wires can be clamped together using a universal type battery connector．This ground must be in place to protect the truck＇s wiring and for efficient operation of the crane．A good ground must exist for the crane to work．This ground wire should be run for all batteries on the vehicle．

8．A boom support is required for this crane．For bodies shorter than 132＂，place the support so that the traveling block hook is secured and does not block the truck cab door．On boom rests supplied by Liftmoore the boom is held down by tension on the hoist wire rope．

9．An outrigger must be installed to keep the crane as level as possible under all expected working conditions．Keeping the crane level reduces the loads on the rotation gear．This will also protect the truck＇s springs，axle and wheels when heavy loads are suspended from the crane．OSHA requirements require a stability test be performed on this installation．A method for performing this test can be found following these instructions．If the installation does not pass the stability test contact Liftmoore for information on derating the crane in the unstable areas．

10．Extra rear spring leaves，heavy coil springs or other devices may be needed to keep the truck level when the crane is mounted on corner or off center locations．

11．Suggested installation drawings are available upon request．

12．When operating the crane for the first time，run the cylinders through their full extension cycle to purge any air from the cylinder．Operate the crane to assure complete operation of all functions．

13．Verify that the anti two－block will stop extension out and winch up when the weight on the device is lifted by either function．

14．Place these instructions and the Owner＇s Manual with Operating Instruction＇s in a convenient place for the user to find and use before operating the crane．

15．Load Chart Decal is to be placed on the truck body for easy visibility by the user．

SUGGESTED WIRING SCHEMATIC FOR 5000 \& 6036 CRANE INSTALLATION:


## VEHICLE STABILITY TEST

OSHA (29CFR 1910.180c) requires a stability test be completed by the installer. A qualified person shall perform this test. Please call Liftmoore for any assistance required in completing this test.

## TEST PREPARATIONS:

- Use as level of a test site as possible.
- Engage parking brake on vehicle.
- Set outriggers, jackstands, or other stability device in place.
- Vehicle tires should remain in contact with the ground.
- The vehicle should be level.


## FILL OUT TEST FORM:

- Complete the Vehicle Information and Crane Information data at the top of Page 2 of this form.
- Use a known weight to determine the Initial Testing Load Radius. Write this number on all 3 locations on Page 2 of this form.


## TEST PROCEDURE:

## Determine Area Y Angle

1. With the crane extended to the Initial Testing Load Radius over the rear of the truck, lift the load. Keep the load less than 4 " off of the ground.
2. Rotate the load counterclockwise. Monitor all vehicle tires to ensure they remain in contact with the test surface.
3. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
4. Use a protractor to determine this angle. Write this angle on the Stability Test Results as Area Y.

## Determine Area W1 Length

5. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
6. Continue rotating the load counterclockwise while monitoring all vehicle tires.
7. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
8. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
9. Repeat this procedure until either the vehicle prevents further rotation or a 180 degree rotation of the load is reached.
10. Record the load radius in feet at this point on page 2 of this form as Area W1 Length.
11. Calculate the W1 \% Rated Capacity.
12. Write the W1 \% Rated Capacity in the Stability Test Results on Page 2 of this form.

## Determine Area Z Angle

13. Return the load to the rear of the vehicle and extend the load to the Initial Testing Load Radius. Keep the load less than 4 " off of the ground.
14. Rotate the load clockwise. Monitor all vehicle tires to ensure they remain in contact with the test surface.
15. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
16. Use a protractor to determine this angle and write this angle on the Stability Test Results as Area Z.

## Determine Area W2 Length

17. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
18. Continue rotating the load clockwise while monitoring all vehicle tires.
19. When one of the vehicle's tires breaks contact with the ground, stop the rotation.
20. Keeping the load off of the ground, retract or elevate the boom until all tires are in contact with the test surface.
21. Repeat this procedure until either the vehicle prevents further rotation or a 180 degree rotation of the load is reached.
22. Record the load radius in feet at this point on page 2 of this form as Area W2 Length.
23. Calculate the W2 \% Rated Capacity.
24. Write the $\boldsymbol{W} \mathbf{2}$ \% Rated Capacity in the Stability Test Results on Page 2 of this form.

## Record Stability Test Results on Placard

25. Record the information from the Stability Test Results on the CRANE TRUCK STABILITY plate (P.N. 18600) and install the plate in a visible position on the vehicle, preferably near the crane.

## THIS TEST IS NOW COMPLETE

## STABILITY TEST FORM

Operational limits of this vehicle


Determine the Testing Load Radius by using the following:


Area W1 Length $\qquad$
Testing Load Radius (ft.) $\qquad$
Multiply by 100 $\qquad$
W1 \% Rated Capacity $\qquad$

Area W2 Length $\qquad$
Testing Load Radius (ft.) $\qquad$
Multiply by 100 $\qquad$
W2 \% Rated Capacity $\qquad$
$180^{\circ}$

## STABILITY TEST RESULTS

| Area Y: | Degrees |
| :---: | :---: |
| Area Z : | Degrees |
| Area W1 Rated Capacity: | \% |
| Area W2 Rated Capacity: | \% |

$\qquad$ Date: $\qquad$

## CRANE SAFETY RULES

## CAUTION!

1. READ AND UNDERSTAND OPERATOR'S MANUAL.
2. INSPECT VEHICLE AND CRANE, INCLUDING ITS OPERATION BEFORE DAILY USE.
3. USE THIS EQUIPMENT ONLY ON SOLID LEVEL GROUND WITH OUTRIGGERS OR JACKSTANDS PROPERLY SET.
4. BEFORE OPERATING THE CRANE REFER TO MAXIMUM LOAD CHART ON CRANE FOR OPERATING LOAD LIMITS.
5. BE SURE LOAD BEING LIFTED IS WITHIN SAFE WINCH CAPACITY AS WELL AS SAFE CRANE CAPACITY. MULTI-PART LINE OPERATION IS REQUIRED WHEN SINGLE LINE LOAD CAPACITY OF WINCH IS EXCEEDED.
6. DO NOT OPERATE, WALK, OR STAND UNDER THE BOOM OR ANY SUSPENDED LOAD.
7. ALWAYS PAY OUT LOAD LINE BEFORE EXTENDING BOOM. WIRE ROPE DAMAGE AND I OR BREAKAGE MAY OCCUR.
8. BOOM MUST BE IN ITS REST BEFORE MOVING VEHICLE.
9. BOOM TIP MUST BE DIRECTLY OVER THE LOAD BEFORE ANY LIFTING IS STARTED. DO NOT DRAG LOADS WITH THIS CRANE.
10. MAINTAIN THIS CRANE AS REQUIRED IN THE OWNER'S MANUAL.
11. DO NOT ALLOW PERSONNEL TO RIDE ON THE LOAD LINE, LOAD, OR BOOM OF THIS CRANE.
12. IT IS UNLAWFUL TO OPERATE THIS EQUIPMENT WITHIN TEN FEET OF HIGH VOLTAGE LINE

## INTRODUCTION

This crane is a powerful machine designed to lift and move heavy loads. There are many hazards associated with these operations. Liftmoore has designed this crane to be as safe as possible but -

## IT IS THE OPERATOR'S RESPONSIBILITY

 TO PREVENT ACCIDENTS!This takes pre-planning, attention, and knowledge of basic principles and rules. Even if you have used similar cranes, reading this manual in its entirety will help prevent damage, injury, or even loss of life; benefits well worth the short amount of time it takes to read these pages.

## REGULATORY AUTHORITY

Use of this crane is governed by OSHA 29 CFR 1910.180 and may be governed by other federal, state, or local regulations.

IT IS THE OPERATOR'S RESPONSIBILITY TO UNDERSTAND AND COMPLY WITH ALL APPLICABLE REGULATIONS GOVERNING THE OPERATION, INSPECTION, AND MAINTENANCE OF THIS CRANE.

Personnel should be trained, tested, and certified, as recommended by OSHA and ANSI standards, before operating this crane.

## USING THIS MANUAL

This manual assumes that the crane is mounted on a typical service body type or similar truck, which is powered by the vehicle electrical or hydraulic system, and is controlled by either the standard pendant control or FM radio control sold by Liftmoore, Inc.

This manual is supplied to provide basic guidelines for the safe use, routine maintenance, and general inspections of this crane.
This manual is supplied to provide basic guidelines for the safe use, routine maintenance, and general inspections of this crane.

Laws, regulations, standards, or policies may be more restrictive than this manual. If a conflict exists for any limit or condition, the safest or most prohibitive shall be used. Under no circumstances shall the load, moment, or stability ratings be exceeded.

Pay particular attention to the following:
WARNING! - Draws attention to hazards, conditions, or procedures that if not observed could result in injury or death.

CAUTION! - Draws attention to hazards, conditions, or procedures that if not observed could result in damage to the crane, load, or other equipment. Equipment failure could in turn lead to injury or death.

NOTE! - Draws attention to conditions or procedures that are essential to emphasize.

For questions, interpretations, or to report errors, please contact Liftmoore, Inc, Engineering Dept.

## OPERATING PRACTICES

## OPERATING RESTRICTIONS

## DUTY CYCLE

For Electric Cranes the duty cycle time should be limited to $10 \%$. This is limited by heat buildup in the motors and declining charge in the batteries. (Installing extra batteries near the crane helps keep the voltage at maximum.)

## PERSONNEL

LIFTING OR MOVING OF PERSONNEL IS STRICTLY PROHIBITED! This crane was neither designed nor intended to lift personnel. Under no circumstances should anyone be allowed to ride on the crane, line, or load. All non-essential personnel must be kept away when using the crane. The load must never be moved over people, nor must anyone be allowed to pass or stand under a suspended load.

## ELECTRICAL LINES

Consult ASME B30.5 for operating procedures, minimum safe distances, and prohibited zones when working around electrical lines or poles.

When operating near electrical power lines, the crane must be positioned so that the distance from the crane to the lines or poles is equal to or greater than the length of the fully extended boom plus the minimum safe distance required.

All parts of the crane, line, and load must be kept a minimum safe distance from electrical power lines and poles. This distance is 10 feet for electrical lines carrying 50kV or less.

## UNDER NO CIRCUMSTANCES SHOULD A CRANE BE OPERATED UNDER ELECTRICAL POWER LINES.

## SETUP

POSITION The vehicle must be positioned so that the load is kept as close to the crane base as possible to reduce the moment on the crane. Consideration must be given to starting and ending position as well as firmness and slope of the ground and any obstructions.

OUTRIGGERS The outriggers or jackstands must be firmly set and the vehicle as level as possible. This will reduce the stresses on the rotation drive and keep the load off the vehicle's suspension. Keep in mind that the weight on the vehicle will shift as the crane and load is rotated.

MANUAL BOOM EXTENSION If the manual extension part of the boom is needed, it must be extended and the boom pin placed in the required position. Insert the pin and replace the pin's hairpin keeper before attempting to lift any load.

LOAD LIMIT The operator must understand the crane load chart. The operator must ensure that the load is within the load limits over the entire range which it will be moved. Be sure to include the weight of any lifting devices including the travel block.

The load limit chart is attached to the side of the crane to aid the operator.

The boom angle indicator and chart aids the operator in determining the load capacity at various boom angles and extensions. It also gives the load limit at that configuration.

STABILITY A stability chart must be posted near the crane. The operator must understand the stability chart. The crane may be de-rated over some areas of its operating radius.

TRAVEL BLOCK The operator must determine if the load is within the single line compatibility of the winch or if a multi-part line configuration is needed.

REEVING Ensure the proper routing of the rope through the sheaves and travel block. The rope must lie in the sheave groove and must not rub against any metal objects.

Ensure the rope is correctly wound on the winch drum. The crane assembly drawing will indicate if the rope must be wound over the top or bottom of the drum. The rope must never contact any part of the winch mounting.

## WARNING!

If the winch winding direction is reversed the brake will not work and the load will fall.

## ATTACHING THE LOAD

POSITION The boom tip must be moved over the load before lifting so that it will be lifted straight up.

## CAUTION!

Never drag a load with the crane. Dragging a load puts very high stresses on the crane for which it was not designed.

ROPE Check the rope condition to ensure it is not frayed or damaged. Ensure that the rope is not kinked and that it does not contact any sharp edges or make any sharp bends.

If using double line configuration, ensure that the lines are not twisted.

## CAUTION!

Never wrap the hoist rope around the load! Serious damage to the rope WILL occur.

HOOK Always make sure the load is applied to the throat of the hook. Never use a bent hook.

## CAUTION!

Always lift with the throat of the hook. Never lift with the load applied to the tip of the hook. Doing so will bend the hook.

SLINGS If the load does not have a lifting eye, use a nylon, chain, or other type of sling designed for lifting and rated for loads greater than that being lifted.

BALANCE Ensure the load will be secure and balanced when lifted. Ensure that the load cannot shift in the sling and that the sling cannot slide across the hook should the load become unbalanced.

## LIFTING THE LOAD

Before lifting, ensure that the load is free from all mountings and is no way attached or stuck to anything.

Ensure that at least five full wraps remain on the winch drum at all times.

Test the winch brake by lifting the load a few inches and ensuring that it does not slip.

## HOLDING THE LOAD

The operator must keep the load in sight at all times once it is lifted.

The operator must never leave the controls once the load is lifted.

The operator must ensure that no one is allowed to pass or stand under a suspended load.

## CAUTION!

Never move the vehicle with a suspended load. Doing so will put dynamic loads on the crane for which it was not designed.

## MOVING THE LOAD

Before moving the load, make sure the path is free of any obstructions or people.

Avoid sudden accelerations or stops. Speeds must be kept to a minimum, especially rotation, to keep the load from swinging.

Avoid sudden reversing of direction. Do not reverse direction while the load is still moving.

Make sure that no part of the crane, boom, or load makes contact with any obstruction or comes within a minimum of ten feet from any electrical line.

## TRANSIT

While in transit, the crane must be stowed, preferably in a boom rest. The crane must be prevented from rotating and the hook prevented from swinging.

## INSPECTION AND MAINTENANCE

OSHA and ASME require frequent and periodic inspections. Records of these inspections must be kept readily available. Liftmoore requires periodic maintenance to ensure proper operation and prolonged life of the crane.

## INSPECTION

## DAILY INSPECTION

OSHA 29CFR 1910.180 (d)(2)(i) requires the following be checked daily prior to use:

- All control mechanisms for maladjustment interfering with proper operation as well as for excessive wear of components and contamination by lubricants or other foreign matter.
- All safety devices for malfunction. This should include the anti-two block and pressure switch.
- Deterioration or leakage in air or hydraulic systems.
- Crane hooks with deformations or cracks. For hooks with cracks or having more than 15 percent in excess of normal throat opening or more than 10 deg. twist from the plane of the unbent hook.
- Electrical apparatus for malfunctioning, signs of excessive deterioration, dirt, and moisture accumulation. This should include the battery terminals, master disconnect switch, electrical swivel
- The wire rope shall be replaced if any of the following conditions are noted:
o Kinking, crushing, birdcaging, or other damage
o Reductions from nominal diameter of more than one-sixty-fourth inch for diameters up to and including five-sixteenths inch, one-thirty-second inch for diameters three-eighths inch to and including onehalf inch.
o Thimble is not in place or is damaged
o Any evidence of heat damage
o Six or more randomly distributed broken wires in 1 lay
o Three or more broken wires in 1 strand in 1 lay


## MONTHLY INSPECTION

A thorough inspection of all ropes in use shall be made at least once a month and a certification record which includes the date of inspection, the signature of the person who performed the inspection and an identifier for the ropes shall be prepared and kept on file where readily available. All inspections shall be performed by an appointed or authorized person. Any deterioration, resulting in appreciable loss of original strength shall be carefully observed and determination made as to whether further use of the rope would constitute a safety hazard. Some of the conditions that could result in an appreciable loss of strength are the following:

- Reduction of rope diameter below nominal diameter due to loss of core support, internal or external corrosion, or wear of outside wires.
- A number of broken outside wires and the degree of distribution of concentration of such broken wires.
- Worn outside wires.
- Corroded or broken wires at end connections.
- Corroded, cracked, bent, worn, or improperly applied end connections.
- Severe kinking, crushing, cutting, or unstranding.


## PERIODIC INSPECTION

An Annual Inspection Form is included in this manual. OSHA 29CFR 1910.180 (d)(2)ii) requires periodic inspections of this crane. Liftmoore recommends an annual inspection using the included form.

## MAINTENANCE PRECAUTIONS

The crane should be maintained monthly for safety reasons and to reduce stress on the crane.

## WARNING!

Never perform any maintenance while the crane has any type of load on it. Use the manual operation procedure to lower the load if necessary.

## WARNING!

Hydraulic cylinders may have high pressure stored in them even after hydraulic power is removed.

The counterbalance and pilot operated check valve in the cylinder will always hold some pressure in the cylinder. Slightly extending the cylinder then retracting a small amount will relieve most of the pressure in the cylinder. DO NOT DEADHEAD THE CYLINDER! This will store the maximum amount of pressure in the cylinder. Care should be taken when either valve is removed from the cylinder as some pressure will still remain.

After any maintenance has been performed the crane shall not be operated until all guards have been reinstalled, all safety devices reactivated, and maintenance equipment removed.

LUBRICATION Refer to the crane specification section for the periodic maintenance schedule and type of lubrication required.

BOLTS Bolts may loosen over time due to vibration; therefore they should be checked periodically. If bolts need to be replaced, make sure they are replaced with bolts of equal or greater strength. Check the periodic maintenance schedule (Crane Specification Section) for bolt specification and torque.

## NOTE!

Sheave and boom and cylinder pivot bolts are not standard bolts. The shank and thread length of these bolts have been modified so that they do not pivot on the threads. Consult the parts section of this manual for part numbers of these bolts.

## OTHER MAINTENANCE

Refer to parts drawings for any specific maintenance or adjustment procedures such as hydraulic winch brake, rotation drive gear set adjustment, Etc..

## MONTHLY INSPECTION REPORT

Crane Model No. $\qquad$ Serial Number $\qquad$

Are Boom Hitch Pins and Keepers in place?
Wire Line Hook with Safety Latch Working?
Is Hook OK, (Not bent)?
Is Thimble on Wire Rope OK?
Is Traveling Block in use?
Is Wire Rope OK, not kinked or frayed?
Are all Boom Sections straight?
Are Sheave Bolts in place and tight?
Do all Sheaves rotate easily?
Are Mounting Bolts tight?
Is Anti Two-Block functioning properly?
Is Boom Angle Indicator in place and functioning and is Chart legible?

Are Cylinder Mounting Bolts secure?
Are Winch Mounting Bolts tight?
When stopped does winch drift less than 1.0 Inches?
Is Load Chart in place and easily read?
Are functions on Pendant operating correctly?
Is Hydraulic Reservoir full?
Is Outrigger straight and functioning?
Yes $\qquad$ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes__ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes No $\qquad$
Yes__ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes_ No $\qquad$
Yes__ No $\qquad$
Yes $\qquad$ No $\qquad$

Yes_ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes__ No $\qquad$
Yes $\qquad$ No $\qquad$
Yes $\qquad$ No $\qquad$
$\qquad$
Yes $\qquad$ No $\qquad$
Yes $\qquad$ No $\qquad$
Any items checked 'No' must be repaired before using this crane.

ANNUAL CRANE CERTIFICATION (29CFR1910.180)
OWNER
MODEL NUMBER SERIAL NUMBER

DATE

Check the following:
__Crane Mounting Bolts (Torque)
__Winch mounting Bolts (Torque)
__Boom mounting bolts
__Cylinder mounting bolts
___Cracks on boom (Check when extended)
$\ldots$ Extension Pads not worn excessively
__Cracks on housing
__ Weld cracks on boom
___Weld cracks on housing
__Boom swing approximately one inch or less at boom tip when retracted
___Hydraulic leaks
___Hoses not chafed or cracked
Sheaves not cracked
__Boom Tip
_Traveling Block
Sheaves not worn excessively
__Boom Tip
_Traveling Block
__Sheaves rotate freely
__Boom Tip
___Traveling Block
__L_Load Chart in place and legible
__Boom angle chart in place and legible
_Labels in place (See manufacturer's chart)
__Crane Hook Throat Opening within 15\% of standard
Crane Hook not bent more than 10 degrees from plane
Hook safety latch operating properly
Booms pin(s) and Keeper(s) in place (Manual Extension Section)
$\qquad$ Wire Rope removed if the following occurs:
Six randomly distributed broken wires in one lay or three broken wires in one strand in one lay.

Wear of one-third the original diameter of outside individual wires.
Kinking, crushing, bird-caging or any other damage.
Evidence of heat damage.
Reduction from nominal diameter of more than one sixty-fourth inch for diameters to five-sixteenths diameter and one-thirty-second inch for diameters three-eighths to onehalf inch.
$\qquad$ Wire Line installed as manufacturer requires.
__Protective covers in place
__Grease crane as required
Check fluid level
__Winch
__Gearbox
__Reservoir

Control system for proper operation
___Winch Up and Down
__Boom Up and Down
__Boom In and Out
__Rotation CW and CCW

Anti Two-Block (Required on Power Extendible Cranes) interrupts:
__Boom Down
__Boom Out
$\qquad$ Winch Up
__Boom Up stopped by Up Limit Switch
__O_Otrigger or jackstand operable
__Outrigger crushing decal in place
__Outrigger and Jackstand operates properly
__Boom rest in place and used
___Load Sensor trips when overloaded
__ Winch Down does not overrun when stopped
__Crane stability chart in place and visible.
I certify that I have performed the above tests and that any deficiencies were corrected and now comply as above.

Signed $\qquad$
Print Name $\qquad$
Company $\qquad$
Address $\qquad$
City $\qquad$ State $\qquad$

| HOIST. With forearm vertical, forefinger pointing up, move hand in small horizontal circle. | LOWER. With arm extended downward, forefinger pointing down, move hand in small horizontal circle. | USE MAIN HOIST. Tap fist on head; then use regular signals. |
| :---: | :---: | :---: |
| USE WHIPLINE (Auxiliary Hoist). Tap elbow with one hand; then use regular signals. | RAISE BOOM. Arm extended, fingers closed, thumb pointing upward. | LOWER BOOM. Arm extended, fingers closed, thumb pointing downward. |


| MOVE SLOWLY. Use one hand to give any motion signal and place other hand motionless in front of hand giving the motion signal. (Hoist slowly shown as example.) | RAISE THEBOOM AND LOWERTHE LOAD. With arm extended, thumb pointing up, flex fingers in and out as long as load movement is desired. | LOWER THE BOOM ANDRAISE THE LOAD. With arm extended, thumb pointing down, flex fingers in and out as long as load movement is desired. |
| :---: | :---: | :---: |
| SWING. Arm extended, point with finger in direction of swing of boom. | STOP. Arm extended, palm down, move arm back and forth horizontally. | EMERGENCY STOP. Both arms extended, palms down, move arms back and forth horizontally. |


| TRAVEL. Arm extended forward, hand open and slightly raised, make pushing motion in direction of travel. | DOG EVERYTHING. Clasp hands in front of body. | TRAVEL (Both Tracks). Use both fists in front of body, making a circular motion about each other, indicating direction of travel, forward or backward. <br> (For land cranes only.) |
| :---: | :---: | :---: |
| TRAVEL. (One Track) Lock the track on side indicated by raised fist. Travel opposite track in direction indicated by circular motion of other fist, rotated vertically in front of body. (For land cranes only.) | EXTEND BOOM (Telescoping Booms). Both fists in front of body with thumbs pointing outward. | RETRACT BOOM (Telescoping Booms). Both fists in front of body with thumbs pointing toward each other. |




# GUI DER RADIO/CAN REMOTE CONTROL SYSTEM 

## I NSTALLATI ON AND OPERATI ON MANUAL

## GUI DER REMOTE

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## DESCRI PTI ON

The GUIDER REMOTE is a state of the art microprocessor based Radio Frequency (RF) control system. It will provide the operator the ability to wirelessly operate equipment. The operator is required to follow all OSHA www.osha.gov and other applicable safety standards when operating the equipment. Do not use high power radio devices in close proximity of this product.

The remote control system consists of: the radio transmitter, main receiver module, engine receiver module, and associated optional equipment such as wiring harnesses.

The transmitter is equipped with a trigger, twist to release E-stop
switch, and toggle switches for the various functions. It includes a port for wired control via the built-in Controller Area Network (CAN) system ${ }^{1}$. This unit runs on a 3.7V rechargeable Li-Ion battery when in wireless mode. When in wired mode, the transmitter runs with power supplied by the CAN cable. This is useful if the battery power gets too low to operate the transmitter but continued operation is needed. The port is also used to charge the internal battery.

The system's radio receiver has both a proportional output and ON/OFF outputs to accommodate the functions available on the transmitter. All outputs are current-sourcing. It also includes a port for wired

[^0]| (CAN) and | RS-232 |
| :--- | :--- | :--- |
| communication for | system | diagnostics.

## OPERATI ON

Power must be applied to the receiver module for the system to work.

Releasing the E-STOP will turn on the transmitter. Pressing the E-STOP button will turn off the transmitter. Pressing the E-STOP will turn off all outputs as a safety feature. If the transmitter goes out of range for more than 2 seconds, all the momentary outputs will turn off as a safety feature, the e-stop output will turn off after 10 seconds.

To operate a proportional output, toggle the switch of the desired function and pull the trigger to the level desired.

* Please note that if the trigger is pulled before the function is selected, the proportional output will not work as a safety feature. Release the trigger and begin again in the proper sequence.

Once the Guider transmitter is on, the operating screen will be displayed. On the top left corner of the screen is transmitter battery display. Plug in the transmitter as soon as possible after seeing the battery symbol turn red. See BATTERY CHARGING below. The top middle of the screen shows the LINK status with the receiver (CAN, RF, or NO LINK), and the top right of the screen shows the system voltage. Load capacity and any errors (if present) are then shown below this when connected to the CRANE receiver. When connected to
the ENGINE receiver, the display will show RUNNING ENGINE FUNCTIONS.

## CONFIGURATION MENU

To navigate to the configuration menu turn the transmitter and receiver off. Press and hold the HORN button then turn on the transmitter. Keep holding the button for greater than 10 seconds until the menu is shown. There are the following options under the configuration menu: TEACH MODE, CLONE TX, SLEEP TIME, RESET TX, and EXIT. To select an option press the HORN button. To scroll down, use the AUX switch and to scroll up, use the RPM switch. To EXIT the configuration menu and go to the operating screen select EXIT.

## TEACH MODE

Select this option to put the transmitter into teach mode and synchronize the receiver and transmitter. See transmitter and receiver synchronization below for more information.

## SLEEP TIME

To save battery life, the transmitter will turn off after 60 minutes no buttons are pressed. The user must press and release the E-STOP at this point to restore transmitter operation. To change the sleep time, select this option and use the RPM and AUX switch to change the number of minutes the transmitter waits to go to sleep. Press the HORN button to save the selected sleep time and exit.

## RESET TX

Warning! If the transmitter is reset, the receiver will have to be re-synchronized to the transmitter for operation! To reset the transmitter select RESET TX then press any button.

## CLONE TX

Warning! This feature can pose a safety hazard for operators if both transmitters are used simultaneously! Use with caution! Occasionally, it is desirable to have more than one transmitter work with a single receiver. This is accomplished by a process called cloning. See CLONING below for more information.

## I NDI CATOR LEDs

The receiver module can identify problems with the system in the form of an error code (red LED will be blinking). Check the decal on the receiver to diagnose system problems. Then, refer to the ERROR CODE CHART in this manual for explanation of the error codes. The green LED indicator will blink on the receiver during active operation. It will turn on solid when the Gate is connected to Wi-Fi.

## TRANSMI TTER AND RECEIVER <br> SYNCHRONI ZATI ON

Each radio remote system is designed to operate with a unique radio ID code and RF channel sequence. Each receiver is programmed to respond only to the transmitter with the correct ID code/RF channel

## GUI DER REMOTE

sequence for which it is set. This feature allows multiple systems to work in close proximity to one another without interference.

In the event that a transmitter becomes damaged and a new one is needed, the receiver can be reprogrammed to respond to the new transmitter. To teach the ID code to the receiver, use the following procedure. *Please note that if this procedure is interrupted before it has completed, the system may have intermittent operation:

For 3B2783A, Crane Receiver:

## TEACH BY CAN CABLE

1. Plug the CAN cable into the CAN port on both the receiver and transmitter and operate a function on the transmitter until the LEDs on the front panel go from steady to flashing for at least 5 seconds. The
units will be synchronized at this point

## TEACH BY RF

1. Turn the transmitter and both receivers off
2. On the transmitter, go to the configuration menu above then select TEACH MODE
3. Apply power to the receiver (engine or crane). The transmitter will display SUCCESFUL and go to operating screen
4. Teach complete

## CLONI NG

Warning! This feature can
pose a safety hazard for
operators if $\quad$ both
transmitters are used
simultaneously! Use with
caution! Occasionally, it is
desirable to have more than one

## GUI DER REMOTE

transmitter work with a single receiver. This is accomplished by a process called cloning. Cloning allows an additional transmitter (B) to have the same ID code as the original transmitter (A). If this feature is desired, use the following procedure:

1. Make sure transmitters and receivers are off
2. On transmitter A, go to the configuration menu above then select TEACH MODE
3. On transmitter B, go to the configuration menu above then select CLONE TX
4. Wait for a few seconds until the screen displays SUCCESFUL
5. Turn off both transmitters
6. Synchronize one of the transmitters to the receivers

If cloning feature has been
invoked and is no longer desired, the ID code of one of the transmitters needs to be changed. This will unclone the transmitters. If this is desired, use the following procedure:

1. Make sure the receiver and transmitters are OFF
2. On the transmitter, go to the configuration menu above then select RESET TX
3. Press any switch again to select a new ID
4. Uncloning complete
5. Use transmitter and receiver synchronization procedure above to link the uncloned transmitter to new receivers

## BATTERY CHARGI NG

The transmitter is designed with a smart battery charger. The battery can be charged by

## GUI DER REMOTE

connecting the CAN cable from the receiver module (powered on) to the port on the transmitter, or by plugging the AC wall charger or DC cigarette charger (minimum 2A @ 12.6VDC) into the port. Red and green LED indicators on the underside of the transmitter indicate the status of the charger: A red LED indicates that the battery is charging and a green LED indicates that the battery is fully charged.

## IMPORTANT BATTERY INFO

When the battery is new, the run-time of the transmitter will be shorter until it has gone through the drain/charge cycle several times. After this point, the unit's current drain should allow at least 20 hours of runtime before a recharge is needed.

The temperature that the transmitter battery is exposed to affects performance and useful life. It is strongly recommended you keep within the following limits:
A. Charging: -4 to $+86^{\circ} \mathrm{F}$
B. Operating: -20 to $+122^{\circ} \mathrm{F}$
C. Storing: -4 to $+86^{\circ} \mathrm{F}$ (lower is better)

## OUTPUTS

Each of the outputs from the receiver module is designed with built-in short circuit and overload protection. The outputs can also detect a noload or broken wire condition.

These error conditions are evident by the alphanumeric display on the receiver module or the HISTOGRAM page on the optional Gate.

The ON/OFF outputs will indicate an error under no load or broken wire status if NOT activated, and will detect a short IF activated. The proportional outputs will detect a no-load or short condition WHEN activated.

## I NPUTS

Digital inputs are available for ATB, BOOM LIMIT, and PRESSURE signals. They will function up to battery voltage levels. One analog input is available for a PRESSURE TRANSDUCER. This expects a signal from $4-20 \mathrm{~mA}$.

## I NSTALLATI ON

Refer to the WIRING CHART in this manual for hookup of the harness.

To install the receiver module, use the two mounting holes
provided on the enclosure to attach it in a vertical manner with the connectors facing down. Please take extra caution not to damage internal components while installing. For high vibration applications, use shock absorbing mounts. It is advised to mount the unit as high as possible, keeping clear of metal obstructions around the antenna which might affect RF performance. Antenna extension cables are available from to aid in this, if needed.

During operation, the crane receiver will generate heat that must be dissipated. The published amps rating can only be fully achieved if adequate cooling is provided. Mount the controller so that the enclosure makes contact with a metallic surface (chassis, cabinet) to conduct the heat and nothing

## GUI DER REMOTE

protrudes through the potting material to damage internal electronic components.

The main power to the receiver should be connected through a switched, fused line capable of a minimum of 20 amps for Engine receiver and 250 amps for Crane receiver. For best results, connect power (+) to the receiver via an auxiliary terminal of the ignition switch, PTO switch, or ignition relay. Be sure that the ground (-) is connected securely to the chassis or battery with a star washer which digs into the base metal to insure good contact.

All connections must be properly insulated to protect against shorts.

Seal all connections with a nonconductive silicone grease to
prevent corrosion.

## BEFORE APPLYI NG POWER!

- Check power and ground for proper polarity.
- Check the wiring harness for possible shorts before connecting to output devices (i.e., valves and relays) by checking each mating pin terminal.
- Verify that the transmitter battery is fully charged.
- Read the rest of this manual.


## SYSTEM <br> TROUBLESHOOTI NG USI NG ON BOARD GATE:

The GATE creates a Wi-Fi access point which allows you to connect to any device with

Wi-Fi and web browser such as smart phones, pads or personal computers. It supports Google Chrome, Internet Explorer, Firefox and IOS Safari and allows user to configure, diagnose and troubleshoot the system.

## ACCESSING THE CONTROL PANEL

1. Turn on the power to the receiver.
2. Use your device and look for the available WiFi networks. A network under the name of "LIFTMOOREXXXXXXXXXX" should be available at
this point, the " $\mathrm{XXXXXXXXXX"}$ should be the 10 digit numeric serial \# on the crane WIFI receiver. Connect to the network, if required password is 3 B 2783 C 1 .
3. Once the connection is established, open a web browser on your device. The Chrome browser is recommended.
4. Enter the address http://192.168.1.1 in the address bar


Address Bar
5. If the Gate is not used for 5 minutes after power up it will automatically turn off. Recycle power to the receiver to turn it back on.
6. The following options are available from the main screen.

## GUI DER REMOTE



## Main Screen

## DIAGNOSTICS

Tap the Diagnostic button to see the diagnostic screens, which shows the present state of remote communications, and system I/O.

When the round circle next to a label is dark, the corresponding ON/OFF input or output is sensed to be active or ON.


Diagnostics

## GUI DER REMOTE

## CALIBRATION

To change the configuration of the unit, tap the Calibration icon.


End user Calibration Page

Password $=1713$

# THIS DRAWING INTENTIONALLY LEFT BLANK FOR FUTURE ADDITIONS OR <br> A PART OR FEATURE IS NOT APPLICABLE TO THIS CRANE 

## THIS DRAWING INTENTIONALLY LEFT BLANK FOR FUTURE ADDITIONS OR <br> A PART OR FEATURE IS NOT APPLICABLE TO THIS CRANE

## GUI DER REMOTE

## HISTOGRAM

Tap the Histogram icon to see a set of screens that show which error codes are active and how many times the specific error code has been active.

This feature can be used to troubleshoot machine wiring and other problems. Tapping the Reset button resets the error code counts. The password to reset error codes is (Contact Liftmoore Inc.). Tap the Home button to return to the main menu.

Note: the GATE is not $a$

## GUI DER REMOTE

## precision measurement instrument. There may be delays.



Histogram Page

The password to gain access to the gate configuration page is (Contact Liftmoore Inc.).

Note: the GATE is not a precision measurement instrument. There may be some delays.


Gate Configuration Page
GATE CONFIGURATION

This page allows you to change the name (SSID) of the $\mathrm{Wi}-\mathrm{Fi}$ network you are connecting to. Factory settings will rename the $\mathrm{Wi}-\mathrm{Fi}$ to its original name.

If Broadcast SSID option is selected, the $\mathrm{Wi}-\mathrm{Fi}$ name (SSID) is public and it will be visible to any other Wi-Fi devices. Otherwise, the Wi-Fi name (SSID) is hidden and it would require manual connection to the network.

If Enable Multiple Connections is selected, multiple connections up to 4 devices could be connected to the GATE. However, only one of

## GUI DER REMOTE

the connected devices can use the GATE. If Single connection is enabled, only one device can be connected to the GATE.

NOTE: A reconnect to the new Wi-Fi connection is needed after each change. It is advised to keep a note of the Wi-Fi name in case if Not Broadcast SSID option is selected. Forgetting the $\mathrm{Wi}-\mathrm{Fi}$ name after selecting this option will require the GATE to be sent to KAR-TECH for RESET.

GUI DER REMOTE

## WI RING CRANE RECEI VER

P1 - DEUTSCH DTM13-12PA

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | ROTATION CW OUTPUT |
| 2 | ROTATION CCW OUTPUT |
| 3 | EXTEND OUT OUTPUT |
| 4 | EXTEND IN OUTPUT |
| 5 | BOOM UP OUTPUT |
| 6 | BOOM DOWN OUTPUT |
| 7 | HOIST UP OUTPUT |
| 8 | HOIST DOWN OUTPUT |
| 9 | N/C |
| 10 | E-STOP OUTPUT |
| 11 | N/C |
| 12 | BOOM UP LIMIT SWITCH INPUT |

P2 - DEUTSCH DT04-4P

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | POWER (9-30V) |
| 2 | BOOM PRESSURE 4-20mA INPUT |
| 3 | ATB INPUT |
| 4 | HORN OUTPUT |

P3 - DEUTSCH DT04-4S

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | POWER (9-30V) |
| 2 | GROUND |
| 3 | CAN HIGH |
| 4 | CAN LOW |

P4 - DEUTSCH DT04-4S

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | POWER (9-30V) |
| 2 | GROUND |
| 3 | CAN HIGH |
| 4 | CAN LOW |


| CON, RECEPTICLE, PLASTIC, CAN |  |
| :---: | :---: |
| PIN | DESCRIPTION |
| A | POWER (9-30V) |
| B | GROUND |
| C | CAN HIGH |
| D | CAN LOW |
| E | SHIELD |

NOTE: MAKE SURE BOTH RED 6GA POWER WIRES ARE CONNECTED TO 9-30V AND 6A BLACK WIRE IS CONNECTED TO GROUND FOR PROPER OPERATION. MAKE SURE ALSO THAT 6GA WHITE WIRES ARE CONNECTED TO THE PUMP.

## WIRING ENGI NE RECEIVER

DEUTSCH DTM13-12PA

| PIN | DESCRIPTION |
| :---: | :---: |
| 1 | GROUND |
| 2 | $\mathrm{~N} / \mathrm{C}$ |
| 3 | $\mathrm{~N} / \mathrm{C}$ |
| 4 | $\mathrm{~N} / \mathrm{C}$ |
| 5 | ENGINE SPEED SELECT DIGITAL INPUT |
| 6 | $\mathrm{~N} / \mathrm{C}$ |
| 7 | $\mathrm{~N} / \mathrm{C}$ |
| 8 | AUXILIARY OUTPUT |
| 9 | ENGINE START OUTPUT |
| 10 | ENGINE STOP OUTPUT |
| 11 | POWE SPEED OUTPUT |
| 12 |  |

## TRANSMI TTER PORT

A POWER
B GROUND
C CAN HIGH
D CAN LOW
E NO CONNECTION

## WI RI NG TI LT AND ROTATI ONAL SENSOR

| DT04-4P-E008 CON/ KT PN: 055-157-0402 |  |
| :---: | :---: |
| PIN | DESCRIPTION |
| 1 | POWER 9-30V |
| 2 | GROUND |
| 3 | CAN HIGH |
| 4 | CAN LOW |

## GUI DER REMOTE

ROUTI NE MAI NTENANCE
Clean transmitter regularly with a damp cloth and mild detergent.

Inspect electrical wiring for wear points or other damage. Repair as required.

Inspect all connections for looseness or corrosion. Tighten and/or "seal" as necessary.

Guider pendants that include a trigger control should be cleaned periodically by blowing air around the trigger area to remove any debris that would prevent proper operation. Apply a light machine oil to the point of rotation when clean.

## MAI NTENANCE PRECAUTI ONS

When performing any inspection
or maintenance work on the remote system, always exercise care to prevent injury to yourself and others or damage to the equipment. The following are general precautions, which should be closely followed in carrying out any maintenance work.

Do not have hydraulic power available to the valves when performing electrical tests.

Never operate or test any function if any person is in an area where they could be hurt by being hit or squeezed by the hydraulic equipment.

Turn power off before connecting or disconnecting valve coils or other electrical loads.

## GUI DER REMOTE

## TROUBLESHOOTI NG

This next section provides basic operator level troubleshooting for the GUIDER REMOTE system. If, after following these instructions, the system still does not function, contact your sales representative for further instructions or servicing.

## TROUBLESHOOTI NG CHART

| PROBLEM | SOLUTI ON |
| :---: | :---: |
| No functions work | 1. Verify transmitter power source - battery, CAN cable, external supply, etc <br> 2. Verify that receiver control module power source is present at its input connector <br> 3. Check for proper system ground <br> 4. Check the receiver or control module LED status display for functionality or errors <br> 3. Check the hydraulic system <br> 4. Check to see if the crane receiver has sufficient cooling. |
| Certain functions do not work | 1. Check the wiring and connections from the receiver control module to the control module to the valve coil for the particular function that does not work <br> 2. Check the receiver control module LED status display for possible fault or error indication <br> 3. Check the hydraulic system <br> 4. Check the electrical system <br> 5. Check to see if the crane receiver has sufficient cooling. |
| Functions operate intermittently | 1. Check for loose connections at the valve coil <br> 2. Check the receiver control module LED status display for functionality or errors <br> 3. Check the receiver antenna for damage |

## GUI DER REMOTE

|  | and possible obstructions |
| :--- | :--- |
|  | 1. Check the hydraulic system |
| 2. Check to see if the crane receiver has |  |
| sufficient cooling. |  |

## GUI DER REMOTE

## ERROR CODES CRANE RECEIVER

| Number of <br> Red <br> LED Blinks | Error Code | Transmitter Display |
| :--- | :--- | :--- |
| 1 | RF Communication Error | RF signal will show red x |
| 2 | Low Truck Battery Error | Truck low batt err |
| 3 | Chassis tilted error | Chassis tilted |
| 4 | Transducer Error | Transducer err |
| 5 | Overload Condition | Overload err |
| 6 | ANTI-TWO-BLOCK Condition | ANTI-TWO-BLOCK |
| 7 | BOOM UP LIMIT Condition | Boom limit err |
| 8 | Rotational Sensor Error | Boom angle sens err |
| 9 | Tilt Sensor Error | Tilt sensor err |
| 10 | HORN Output Error | Horn err |
| 11 | ROTATE CW Output Error | Rotate CW err |
| 12 | ROTATE CCW Output Error | Rotate CCW err |
| 13 | EXTEND OUT Output Error | Extend out err |
| 14 | EXEND IN Output Error | Extend in err |
| 15 | BOOM UP Output Error | Boom up err |
| 16 | BOOM DOWN Output Error | Boom down err |
| 17 | HOIST UP Output Error | Hoist up err |
| 18 | HOIST DOWN Output Error | Hoist down err |
| 19 | E-STOP Output Error | E-STOP out err |
| 20 | SPEED Output Error | Speed out err |
| 21 | SPEED Output High Current | Overcurrent err |
| 22 | Error | TRIGGER Input Error |
| 23 | TRIGGER before Switch Error | Trigger err |

## Error code explanations:

1 Transmitter is off
Transmitter went to sleep mode
Interference in RF communication link
2 System voltage is below 11 V ( 12 V system)

## GUI DER REMOTE

3
If the chassis is tilted over five degrees, all functions are reduced to slow speed. The following outputs will also be disabled: Boom Down, Hoist Up, and Extend Out.

4 No voltage present at pressure input or voltage is out of specified range ( $4-20 \mathrm{~mA}$ )

5 Overload condition based on Gate setting is present
Anti-Two Block condition present, ATB input is low
Boom Limit input active, BOOM LIMIT input is low
No CAN messages are being received from Tilt sensor. Check wiring

9 No CAN messages are being received from Rotational sensor. Check wiring

10-20 Short or open load/coil on output
21 Current at SPEED output is above rated current, output will turn off

22 No voltage present on trigger in transmitter
23 Trigger was pulled on transmitter before switch was activated

## GUI DER REMOTE

## ERROR CODES ENGI NE RECEI VER

| EC | POSSIBLE CAUSE |
| :---: | :--- |
| 1 | RF COMMUNICATION ERROR |
| 2 | ENGINE SPEED OUTPUT ERROR |

## Error code explanations:

1 Transmitter is off
Transmitter went to sleep mode
Interference in RF communication link
2
Short or open load/coil on output

## PARTS LIST

| PART NUMBER | DESCRI PTI ON |
| :--- | :--- |
| 3B2782B | RADIO TRANSMITTER |
| 3B2783D | CRANE RADIO RECEIVER |
| 3B2784A | ENGINE RADIO RECEIVER |
| $\mathbf{0 2 0 - 5 0 6 - 0 2 5 0 ~}$ | CAN ADAPTOR CABLE 25' |
| B20032B | CHARGER, 12 VDC CIGARETTE LIGHTER PLUG |
| B20072A | FAST CHARGER SUPPLY, 110V AC WALL |
| A3003EA | TILT SENSOR |
| A3003FA | ROTATIONAL SENSOR |

There are no user-serviceable parts inside the transmitter or the receiver. Return the units for service.

Note: For operation with negative ground systems only.

## WARNI NG:

The GUIDER REMOTE must be operated in compliance with all applicable safety regulations, rules, and practices. Failure to follow required safety practices may result in death or serious injury.

The information, specifications, and illustrations in this manual are those in effect at the time of printing. We reserve the right to change specifications or design at any time without notice.

## GUI DER REMOTE

## TRANSMI TTER PI CTORI AL



ERROR CODES).


## CRANE RECEIVER PICTORIAL



## GUI DER REMOTE

ENGI NE RECEI VER PI CTORI AL


## GUI DER REMOTE

## TI LT, CHASSI S SENSOR PI CTORIAL



## GUI DER REMOTE

## ROTATI ONAL, BOOM SENSOR PI CTORI AL



## GUI DER REMOTE

## SPECI FI CATI ONS

FCC ID: P4U-MOD164<br>Industry Canada Certification Number: 4534A-MOD164<br>EQUIPMENT CLASS: PART 15 SPREAD SPECTRUM TRANSMITTER

## TRANSMI TTER

Power supply
3.7V Li-Ion Rechargeable Battery

Fast charger temperature range
$+5^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$

Operating temperature - Radio..................................... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage temperature ............................................... $-40^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
RF Frequency ..................................................................... 902-928 MHz
RF Transmit power (EIRP) ........................................................... 100 mW
LCD display operating range (if equipped) ......................... $20^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
Vibration 3G to 200 Hz
Shock.................................................................................................. 50G
NEMA .................................................................................................. 12

## RECEIVER

Power supply voltage................................................................. 9-30VDC
Operating temperature $\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots{ }^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage temperature ................................................ $-40^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$
Outputs ......................................................... 5.0A max each, sourcing
Pump Output........................................................... 250A max, sourcing
Digital Inputs (when equipped) .......................................... supply voltage
Analog Inputs (when equipped)........................................ 0-5VDC/4-20mA
RF Frequency .................................................................... 902-928 MHz
Vibration.............................................................................. 3G to 200Hz
Shock............................................................................................... 100G
NEMA .....................................................................................................4X

## GUI DER REMOTE

## I NSTRUCTI ON TO THE USER

This equipment has been tested and found to comply with the limits for a class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates radio frequency energy and if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

* Reorient or relocate the receiving antenna.
* Increase the separation between the equipment and receiver.
* Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
* Consult the dealer or an experienced radio/TV technician for help.

This equipment has been certified to comply with the limits for a class B computing device, pursuant to FCC Rules. In order to maintain compliance with FCC regulations, shielded cables must be used with this equipment. Operation with non-approved equipment or unshielded cables is likely to result in interference to radio and TV reception. The user is cautioned that changes and modifications made to the equipment without the approval of manufacturer could void the user's authority to operate this equipment.

3-2
KAR-TECH 28791 RECEIVER - REV C-E
SOFTWARE PROGRAM 3Z8345DX - HISTOGRAM PAGE
11/25/2020

| Error Name | CONDITION FOR ERROR | TRANSMITTER DISPLAY | RECEIVER DISPLAY | HISTOGRAM PAGE | DIAGNOSTICS PAGE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LOW TRUCK BAT ERR | 1) any drop in system voltage | LOW TRUCK BAT ERR | ERROR CODE: 02 | THE ERROR DOESN'T REMAIN ACTIVE. IT CLEARS INSTANTLY | DISPLAYS ALL INPUT AND OUTPUT SIGNALS |
| E-STOP ERR <br> CHASSIS TITLED ERR (WITH THE DUAL AXIS SENSOR CALIBRATED) | 1) disconnected the dual axis (tilt) sensor | TILT SENSOR ERR, CHASSIS TILTED | ERROR CODE: 03 | CHASSIS TILTED ERR, CHASSIS ANGLE SENSOR ERR | N/A |
|  | 2) SET TILT SENSOR BEYOND $5^{\circ}$ IN ANY DIRECTION | CHASSIS TILTED | ERROR CODE: 03 | CHASSIS TILTED ERR | Y-ANGLE ON TILT SENSOR IS $7^{\circ}$ |
| E-STOP ERR <br> CHASSIS TITLED ERR (WITH THE DUAL AXIS SENSOR CALIBRATED AND PHYSICALLY CONNECTED) | disconnected (pin 10), white w/blue striped wire to e-stop solenoid. 1A) TOGGLES IN NEUTRAL | TILT SENSOR ERR, CHASSIS TILTED | ERROR CODE: 03 | CHASSIS TILTED ERR, CHASSIS ANGLE SENSOR ERR | RECEIVER CAN INPUTS N/A, BOOM ANGLE -180 |
|  | ALL LIMITING FUNCTIONS: 1B) HOIST UP, 1C) BOOM DOWN AND 1D) EXTEND OUT. (B-D) ALL THROWN AND HELD INDEPENDENTLY | TILT SENSOR ERR, CHASSIS TILTED | ERROR CODE: 03 | CHASSIS TILTED ERR, CHASSIS ANGLE SENSOR ERR |  |
|  | ALL NON-LIMITING FUNCTIONS: 1E) HOIST DOWN, 1F) BOOM UP, 1G) EXTEND IN, 1H) CW ROTATION AND 1I) CCW. (E-I) ALL THROWN AND HELD INDEPENDENTLY | BOOM ANGLE SENS ERR, OVERLOAD ERR, TILT SENSOR ERR, CHASSIS TILTED | ERROR CODE: 03 | CHASSIS TILTED ERR, OVERLOAD ERR, BOOM ANGLE SENSOR ERR, CHASSIS ANGLE SENSOR |  |
| TRANSDUCER ERR | 1) red wire (pin A) disconnected only | TRANSDUCER ERR | ERROR CODE: 04 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 2) black wire (pin B) disconneted only | NO ERROR | NO ERROR CODE | NO ERROR DISPLAYED | DISPLAYS ALL INPUT AND OUTPUT SIGNALS |
|  | 3) white wire (pin C) disconnected only | TRANSDUCER ERR | ERROR CODE: 04 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 4) red wire (pin A) plugged in only | TRANSDUCER ERR | ERROR CODE: 04 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 5) black wire (pin B) plugged in only | TRANSDUCER ERR | ERROR CODE: 04 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 6) white wire (pin C) plugged in only | TRANSDUCER ERR | ERROR CODE: 04 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
| OVERLOAD ERR | 1) dead head boom up cylinder by removing the up limit switch | OVERLOAD ERR | ERROR CODE: 05 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | ALL TESTS WERE IDENTICAL FOR OVERLOAD ERR. (BOOM ANGLE 770) |  |  |  |  |
| ANTI-TWO BLOCK ERR | 1) red wire disconnected only | ANTI-TWO BLOCK | ERROR CODE: 06 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 2) black wire disconneted only | ANTI-TWO BLOCK | ERROR CODE: 06 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 3) both wires disconnected from 1 and 2. | ANTI-TWO BLOCK | ERROR CODE: 06 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |

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| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 4) boom tip disconnected | ANTI-TWO BLOCK | ERROR CODE: 06 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
| BOOM UP LIMIT ERR | 1) red wire disconnected only | BOOM LIMIT ERR | ERROR CODE: 07 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 2)white disconnected only | BOOM LIMIT ERR | ERROR CODE: 07 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 3) both disconnected | BOOM LIMIT ERR | ERROR CODE: 07 | ACTIVE ERROR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 1) RAISE THE BOOM TO MAX HEIGHT (BOOM ANGLE $73^{\circ}$ ) | BOOM LIMIT ERR | ERROR CODE: 07 | ACTIVE ERROR | BOOM UP SWITCH NO LONGER ACTIVE. DOES NOT DISPLAY ALL OUTPUT SIGNALS** |
| BOOM ANGLE SENSOR ERR | 1) disconnected (pin 1), the power wire only | BOOM ANGLE SENS ERR OVERLOAD ERR | ERROR CODE: 05 | TWO ACTIVE ERRORS | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 2) disconnected (pin 2), the ground wire only | BOOM ANGLE SENS ERR OVERLOAD ERR | ERROR CODE: 05 | TWO ACTIVE ERRORS | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 3) disconnected (pin 3), the can high wire only | BOOM ANGLE SENS ERR OVERLOAD ERR | ERROR CODE: 05 | TWO ACTIVE ERRORS | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 4) disconnected (pin 4), the can low wire only | BOOM ANGLE SENS ERR OVERLOAD ERR | ERROR CODE: 05 | TWO ACTIVE ERRORS | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
| TILT SENSOR ERR | 1) Rotate tilt sensor above $5^{\circ}$ | CHASSIS TILTED | NO ERROR CODE | NO ERROR DISPLAYED | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 2) disconnected (pin 1), the power wire only | TILT SENSOR ERR CHASSIS TILTED | ERROR CODE: 09 | CHASSIS ANGLE SENSOR ERR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 3) disconnected (pin 2), the ground wire only | TILT SENSOR ERR CHASSIS TILTED | ERROR CODE: 09 | CHASSIS ANGLE SENSOR ERR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 4) disconnected (pin 3), the can high wire only | TILT SENSOR ERR CHASSIS TILTED | ERROR CODE: 09 | CHASSIS ANGLE SENSOR ERR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
|  | 5) disconnected (pin 4), the can low wire only | TILT SENSOR ERR CHASSIS TILTED | ERROR CODE: 09 | CHASSIS ANGLE SENSOR ERR | DISPLAYS ALL INPUT SIGNALS BUT NOT ALL OUTPUT SIGNALS** |
| HORN OUT ERR | 1) + wire disconnected only | HORN ERR | ERROR CODE: 10 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | HORN ERR | ERROR CODE: 10 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | HORN ERR | ERROR CODE: 10 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| ROT CW OUT ERR | 1) + wire disconnected only | ROTATE CW ERR | ERROR CODE: 11 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | ROTATE CW ERR | ERROR CODE: 11 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | ROTATE CW ERR | ERROR CODE: 11 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |

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| :---: | :---: | :---: | :---: | :---: | :---: |
| ROT CCW OUT ERR | 1) + wire disconnected only | ROTATE CCW ERR | ERROR CODE: 12 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | ROTATE CCW ERR | ERROR CODE: 12 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | ROTATE CCW ERR | ERROR CODE: 12 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| EXT OUT OUT ERR | 1) + wire disconnected only | EXT OUT ERR | ERROR CODE: 13 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | EXT OUT ERR | ERROR CODE: 13 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | EXT OUT ERR | ERROR CODE: 13 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| EXT IN OUT ERR | 1) + wire disconnected only | EXT IN ERR | ERROR CODE: 14 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | EXT IN ERR | ERROR CODE: 14 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | EXT IN ERR | ERROR CODE: 14 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| BOOM UP OUT ERR | 1) + wire disconnected only | BOOM UP ERR | ERROR CODE: 15 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | BOOM UP ERR | ERROR CODE: 15 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | $3)$ both wires disconnected | BOOM UP ERR | ERROR CODE: 15 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| BOOM DN OUT ERR | 1) + wire disconnected only | BOOM DOWN ERR | ERROR CODE: 16 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) - wire disconnected only | BOOM DOWN ERR | ERROR CODE: 16 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) both wires disconnected | BOOM DOWN ERR | ERROR CODE: 16 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| HOIST UP OUT ERR | 1) disconnected (pin 7), the blue wire at contactor | HOIST UP ERR | ERROR CODE: 17 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 2) disconnected the yellow ground wire | HOIST UP ERR | ERROR CODE: 17 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 3) disconnected 6 gauge ground wire | HOIST UP ERR HOIST DOWN ERR | ERROR CODE: 17 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
| HOIST DN OUT ERR | 1) disconnected (pin 8), the black wire at contactor | HOIST DOWN ERR | ERROR CODE: 18 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  | 1) disconnected 6 gauge ground wire | HOIST UP ERR HOIST DOWN ERR | ERROR CODE: 17 | ACTIVE ERROR* | DISPLAYS INPUT AND OUTPUT SIGNAL |

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| :---: | :---: | :---: | :---: | :---: | :---: |
| E-STOP OUT ERR (NO DUAL AXIS SENSOR CALIBRATED OR CONNECTED) | 1) disconnected (pin 10), white w/blue striped wire to e-stop solenoid. | with the transmitter OFF, NO ERROR | ERROR CODE: 19 | ACTIVE ERROR | N/A |
|  |  | with the transmitter ON, NO ERROR | NO ERROR CODE | NO ACTIVE ERROR WITH TOGGLES IN NEUTRAL POSITION | DISPLAYS INPUT AND OUTPUT SIGNAL |
|  |  | ALL TESTS WERE IDENTICAL FOR DISCONNECTING PIN 10 FROM THE E-STOP SOLENOID |  |  |  |
| SPEED OUT ERR | 1) disconnected power line from receiver to pump | SPEED OUT ERR | ERROR CODE: 20 | ACTIVE ERROR | DISPLAYS INPUT AND OUTPUT SIGNAL |
| SPEED OUT HIGH CURRENT ERR |  |  |  |  |  |
| TRIGGER INPUT ERR | 1) disconnected trigger harness on transmitter | TRIGGER ERR | ERROR CODE: 23 | ACTIVE ERROR ONLY WHEN SWITCH IS THROWN | DISPLAYS INPUT AND OUTPUT SIGNALS |
| TRIGGER INPUT BEFORE SW ERR | 1) hold down the proportional control trigger before throwing a toggle. | TRIGGER START ERR | ERROR CODE: 24 | ACTIVE ERROR ONLY WHEN SWITCH IS THROWN | DISPLAYS INPUT AND OUTPUT SIGNALS |

* Active errors are displayed in the histogram when the toggle switch is in neutral. For error codes 10-18, the error code resets when the toggle switch is thrown for the associated function.
** For error codes (04-09) , the three limiting functions: hoist up, extend out and boom down do not engage the pump when the toggle for that function is thrown. Also, the error code on the transmitter, receiver and histogram does not reset when the toggle is thrown for the associated function. (Note: EC06 error code will only disengage Winch up and Extend out on 2010, 3612, 5000 \& 6036 cranes).

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IFTMOORE

## SAFETY SYSTEM

The safety system is designed to help prevent damage to the crane that would be caused by overload or two-blocking. The system consists of a load sensor, anti-two block device (optional on smaller, electric cranes), and limiting system control board.

When the applicable switch detects an overload or two-block condition, the limiting system will prevent activation of winch up, boom down, and extend out since these directions would cause damage. Winch down, boom up, extend in, and power rotation will still function so that the crane can be moved to a safe configuration.

## CAUTION!

Never de-activate or override safety functions. Doing so can result in serious damage to the crane and possibly injury or death.

## LOAD SENSOR

A pressure activated switch in the elevation cylinder acts as a load sensor. This switch is normally closed and opens at the preset pressure corresponding to the load rating of the crane.

## CAUTION!

The load sensor will not function when the elevation cylinder is fully retracted and is inaccurate when the boom is below horizontal.

## CAUTION!

The operator must never rely strictly on the load sensor to determine overload conditions. The load and load limits must always be known and adhered to.

## ANTI-TWO BLOCK

The anti-two block device (optional on smaller electric cranes), mounted on the boom crown plate, consists of a normally open switch actuated by a lever. A weight is attached to the lever and holds the switch
closed. If the weight is lifted by the hook or travel block the switch opens.

The power and signal wires are wired through the cord reel, which is in turn wired to the ATB switch.

## LIMITING SYSTEM CONTROL

The limiting system control prevents output of winch up, boom down and extend out if it is not receiving a signal from either the ATB or load sensor.

The ATB does not trip boom down when winch is mounted on the boom.

There is a one second delay before deactivation of boom down when the load sensor is tripped to prevent false readings caused by pressure spikes.

## MISCELLANEOUS

## UP LIMIT SWITCH

The up limit switch prevents the elevation cylinder from reaching full extension. If the elevation cylinder were to "dead-head", the resulting pressure would activate the load sensor, preventing boom down. The boom would then have to be lowered using the manual operation buttons on the solenoid valves.

## CIRCUIT BREAKER, FUSE

For electric cranes a 150 Amp circuit breaker is supplied with the crane. It should be installed as close to the battery as possible. For hydraulic cranes a 10 Amp blade type fuse is supplied.

## DISCONNECT SWITCH

A power disconnect switch is supplied with the crane. Power to the crane should be turned off whenever not in use. This is to prevent inadvertent or unauthorized use and will help prevent corrosion at electrical connections.

## ELECTRIC HOIST

Permanent Magnet Motor
This Liftmoore crane features an electrically driven planetary gear hoist. The hoist is powered in both directions and features an automatic internal brake to positively control the load.

The hoist is permanently lubricated at the factory. Barring damage or part replacement, no further lubrication is necessary.

## MOTOR

The hoist motor is a permanent magnet, reversible, direct current (DC) motor.

## CAUTION!

The hoist motor is rated for intermittent duty. Duty cycle is limited to 5 minutes in 30 to allow the motor to cool. Extended use can damage the motor.

## CAUTION!

When the motor approaches stall, a very rapid heat build up occurs which can cause permanent motor damage. Discontinue use when the motor speed is reduced excessively by voltage drop or load.

## BRAKE

The hoist features a single acting, overrunning brake. It automatically activates to hold the load and assist in lowering the load.

## WARNING!

The hoist brake only functions in one direction. If the hoisting direction is reversed by reversing the rope winding direction the brake will not hold and the load will fall. Serious injury or death could occur.

The brake is factory set and is not adjustable. If the brake fails to hold the load or if downward drift becomes excessive the brake must be replaced.

## DIRECTIONAL CONTROL

Motor direction is controlled by either a solenoid pack or sealed contactor. Schematically, they are identical - two double pole-double throw solenoids are used to reverse polarity to the motor terminals.

Signal voltage, controlled by the pendant, energizes the selected directional solenoid, directing power to the winch terminal through the normally open terminal. The other terminal remains grounded through the normally closed terminal of the other solenoid.


## HYDRAULIC SYSTEM FOR ELECTRIC CRANES

The hydraulic system consists of the hydraulic pump, manifold, solenoid valves, cylinders, motors, and tubing and hoses. Hydraulic power is generated by the electrically driven hydraulic pump on the outside of the housing. The hydraulic system is plumbed in series so that more than one function can be operated simultaneously.

## PUMP

The hydraulic pump assembly consists of a DC permanent magnet electric motor, pump, and reservoir.

The motor is activated by the pump solenoid. The solenoid is energized by the pendant control whenever a hydraulic function is activated.

The pump provides fluid pressure to power hydraulic functions. The system incorporates an adjustable relief valve to prevent damage that can be caused by over pressurizing the system.

Fluid is drawn from and returned to the reservoir. Servicing the hydraulic pump consist of maintaining the oil level. The reservoir should be kept as full as possible to prevent condensation from forming inside the tank. Also ensure the oil is not contaminated by water, dirt, rust, etc. See crane specification sheet for hydraulic oil type.

## SOLENOID VALVES

Each hydraulically operated function is controlled by a 4 -way, 3-position (open and close) center solenoid valve. It is electrically operated and spring biased to center. A manual operation button is incorporated in the coil-retaining nut. Valves are mounted to the series manifold.

## CYLINDERS

Most hydraulic cylinders are double acting cylinders with integrally mounted counterbalance valve and pilot operated check valves. Refer to the cylinder drawings for specific information.

All cylinders use a counter-balance load holding cartridge valve on the extend port.
This valve performs 3 functions:

- Controls the rate of decent when lowering the load
- Keeps load from falling in the event of sudden loss of system pressure, such as when a hose bursts.
- Acts as a relief valve to prevent damage from induced load or thermal expansion.

It allows free flow to extend then blocks flow until opened by pilot pressure to the retract port or when the relief pressure is reached.

Some cylinders utilize a pilot operated check valve on the retract port to prevent the cylinder from creeping out under no load conditions. This valve allows flow into, but prevents flow from the retract port, thus hydraulically locking the cylinder until opened by pilot pressure to the extend port.

## MOTORS

## THE HYDRAULIC MOTOR USED BY THE ROTATION DRIVE IS A HIGH-TORQUE, LOW-SPEED CONSTANT DISPLACEMENT MOTOR. MANUAL OPERATION

If electrical problems occur the solenoid valves may be operated manually by depressing the manual operation button incorporated in the coil-retaining nut. Using a blunt object such as a bolt or screwdriver handle may be required to assist operation if high pressures are needed. Refer to the manifold drawing for function valves and directions.

If possible, activate the pump by activating a hydraulic function on the pendant. If this does not work, then energize the pump solenoid using a jumper from the hot side of
the solenoid to the coil post where the WHT/BLK wire is connected. If this fails also then battery voltage can be applied directly to the pump motor.

If hydraulic power is lost while a load is suspended, the load can be lowered by decreasing the setting on the counterbalance valve. This should only be done in extreme cases. The valve must be reset before the crane is returned to use.

## WARNING!

The boom may fall if the adjustment is made too fast. Do not stand where the boom may hit you if it falls. Serious injury or death may result

## WARNING!

The area between the boom and the cylinder, the boom and the housing, and the cylinder and the housing will change as the boom position changes and could form pinch points. Do not position any part of your body in these areas as it may be pinched or crushed as the boom lowers.

To decrease the setting, loosen the locknut on the valve, then slowly turn the adjustment stem CLOCKWISE until the load begins to lower. Count the number of turns so that the valve can be returned to its original setting.

Alternately, a pressure gage must be put on the retract port to adjust the setting so that approx. 1800 PSI is required to lower the boom with no load.

Test the setting by lifting a known load near the moment rating.

## TROUBLESHOOTING SAFETY SYSTEM

DTCH Relay Card

To check functions controlled by the safety system check the status indicators. (See Relay Box Assembly drawing.) If only one of the safety functions is not working, activate that function and check for error codes and/or its output status indicator.

For non-FM systems, if the status indicator lights then the problem is in the wiring or in the solenoid coil. If the light does not illuminate, check the control pendant. If the control pendant is good then the crane control module needs to be replaced.

For FM systems, check for error codes. If none are present, see the FM Troubleshooting section.

If boom out, boom down and winch up are not working, confirm that the control board has power. Confirm that the board is receiving a signal from the ATB and load sensor.

If the error code is active, ensure that the crane is not overloaded and that the ATB lever is holding the switch closed. Check for voltage at the ATB and Load Sensor inputs.

## CHECK LOAD SENSOR SWITCH

If the load sensor input is not receiving voltage, locate the load sensor connector inside the crane housing. The plug side will have a red wire and a gray wire, the receptacle side will have a red and a white wire.

Disconnect and check for continuity between the two pins on the receptacle (switch side). If there is no continuity then the load sensor is bad and needs to be replaced.

## CHECK ATB SWITCH

If the ATB input is not receiving voltage remove the ATB housing cover and disconnect the connector. Check for continuity on the switch side. Lifting the weight should break the continuity. If either of these conditions is incorrect the switch is bad and needs to be replaced.

## CHECK CORD REEL

Check the ATB switch if not done so already. Locate the ATB connector inside the crane housing. The plug side will have a red wire and a black wire. The receptacle side will have a white wire and a black wire.

Disconnect the plug going to the switch. Check for continuity between the two pins on the receptacle. Have someone lift the weight on the ATB and continuity should be broken. If either of these conditions are incorrect then the cord reel is bad and needs to be replaced.

## CHECK POWER TO SAFETY SWITCHES

If the safety switch is good, check for voltage at pin 1 (the red wire) on the plug. If there is no voltage, follow the wire back to the 6 -pin power distribution plug, checking for breaks or shorts.

Remove the power distribution receptacle (cap).

## NOTE!

Removing the cap will disconnect power to all electrical components. Be sure to replace the cap before continuing.

Check the cap for bent pins. Check that all wires are fully seated in the plug. If they are not, then remove the green locking wedge and push the wires forward until seated. Reinstall the wedge ensuring that no wires are pushed back.

## TROUBLESHOOTING ELECTRIC HOIST

Permanent Magnet, Contactor Controlled

## IMPORTANT NOTE!

The importance of first physically checking every connection between the battery and the crane cannot be overstressed!

Poor connections or poor grounding account for a large percentage of hoist problems. Time is often wasted chasing other probable causes only to eventually find a loose or corroded connection. Measuring the voltage is not sufficient. Often a poor connection will allow enough amperage to operate a meter or test light, but not enough to operate the hoist, which requires very high amperage.

If the problem is random and intermittent then it is almost assuredly a loose or bad connection.

Another common problem is low battery voltage. Even if the battery is good when troubleshooting begins, running the winch can quickly drain a battery. If it can be done safely, it is best to have the vehicle running.

Also check the control socket and plug for bent, corroded, or dirty pins.

## CAUTION!

As the motor approaches stall, due to low voltage or excessive load, a very rapid heat build up occurs which will quickly damage the motor. If the motor is not turning, do not operate the switch for more than a second. Allow the motor to cool between attempts to make it run.

## HOIST OPERATES IN ONLY ONE DIRECTION

If the hoist only operates in one direction swap the control wires on the contactor.

Activating the pendant switch in the working direction should now operate the hoist in the previous non-working direction.

Example: if hoist up is not working, after swapping the control wires activating the hoist down switch should cause the hoist to go up.

If it does then the hoist and contactor are working correctly and the problem is in the pendant crane socket or wiring. If it does not then the problem is the contactor or brake.

If the motor tries to turn but stalls then the problem is most likely the brake. Also, if the contactor makes a clicking noise then that is a good indication that it is working and, again, the problem is most likely the brake.

If the control wires were swapped in the previous step, return them to their original positions. Swap the motor wires (labeled 1 and 2). It is usually easiest to swap them at the motor.

Activating the pendant switch in the working direction should now operate the hoist in the previous non-working direction.

Example: if hoist up is not working, after swapping the motor wires activating the hoist down switch should cause the hoist to go up.

If it does, then one side of the contactor is not working and it needs to be replaced.

If it does not work, the problem is a brake malfunction. Inspect the brake installation. Correct any problems found. The brake cannot be repaired. Replace if any damage is found.

## HOIST DOES NOT RUN IN EITHER DIRECTION

If the hoist does not run in either direction then the problem is either lack of power to the control socket or pendant, lack of sufficient power to the motor, or hoist brake malfunction or motor failure.

If the contactor clicks when the switch is activated then the control socket is getting power.

If all connections have not been checked, do so now. Also ensure that the battery still has sufficient power. As a rule of thumb, if it has enough power to start the engine, then it is good.

Activate the winch toggle switch and check for voltage at motor contacts. If positive voltage is measured at both terminals, the problem may be the ground wire from the contactor. Check for tightness or corrosion on this wire.

Once sufficient power is ensured, if there is any indication that the motor is trying to turn but stalls the problem is the brake - have it replaced.

If there is no indication that the motor is trying to turn and the contactor has been tested, then replace the motor.

## TESTING THE PENDANT AND CONTROL WIRING

If the problem is narrowed to the control wiring, it is most likely caused by a cut or disconnected wire. A visual inspection of the
wiring should be made and repairs made as necessary.

Refer to the schematic and pendant drawing for pin functions and locations.

If no visual defects are found and if a continuity tester is available, disconnect the pendant and check for continuity between the control socket pin and terminal at the contactor.

Alternately, a piece of wire or metal object may be used to short between the control socket power pin and the socket hoist pin(s). If the hoist operates then the problem is in the pendant.

If not, check for power at the control socket power pin. If there is no power, trace the wiring back, checking each connection until the problem is found. Correct as necessary.

## TROUBLESHOOTING HYDRAULIC PUMP

Electric Pump, 14P Socket

## IMPORTANT NOTE!

The importance of first physically checking every connection between the battery and the crane cannot be overstressed!

Poor connections or poor grounding account for a large percentage of electrical problems. Time is often wasted chasing other probable causes only to eventually find a loose or corroded connection. Measuring the voltage is not sufficient. Often a poor connection will allow enough amperage to operate a meter or test light, but not enough to operate the motor, which requires very high amperage.

If the problem is random and intermittent then it is almost assuredly a loose or bad connection.

Another common problem is low battery voltage. Even if the battery is good when troubleshooting begins, running the motor can quickly drain a battery. If it can be done safely, it is best to have the vehicle running.

Also check the control socket and plug for bent, corroded, or dirty pins.

## CAUTION!

As the motor approaches stall, due to low voltage or excessive load, a very
rapid heat build up occurs which will quickly damage the motor. If the motor is not turning, do not operate the switch for more than a second. Allow the motor to cool between attempts to make it run.

## FOAMY FLUID

If the fluid foams then the problem is the pump seal - have it replaced.

## PUMP DOES NOT RUN

If both the pump and winch are not working, the problem is power related or control wiring related. Troubleshoot those areas first.

If the solenoid is actuating it will make a clicking noise. If the solenoid is not clicking, check for power at the coil input (small screw terminal) on solenoid when the Boom Up switch is activated. If there is no power then the problem is the electrical wiring harness or pendant control wiring.(refer. to CONTROL TROUBLESHOOTING CHART).

If the coil is getting power when the switch is activated, but not clicking then the problem is most likely the solenoid.

If the solenoid is clicking check for full power input to the solenoid. Trace the wiring back to the crane input, checking for power at each connection until the problem is found. If full electrical power to the motor is confirmed then the motor is faulty and should be replaced.

## DEUTSCH CONNECTIONS \& PINS



F2435-A
11/27/17
I:IFORMS

## SECTION

## CRANE SPECIFICATIONS MODEL 6036DX-22 CRANE

MOMENT RATING
MAX SINGLE LINE LOAD
MAX DOUBLE LINE LOAD

36000 FT-LBS

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3000 \text { LBS }
$$

$$
6000 \text { LBS }
$$

LIFTING CAPACITIES AT VARIOUS LOAD RADII


POWERED FUNCTIONS AND EXPECTED TIMES

| WINCH | UP: | 2.9 s | DOWN: 3.1 s | 1 REVOLUTION |
| :--- | :--- | :--- | :--- | :--- |
| BOOM ELEVATION | UP: | 25.5 s | DOWN: 34.4 s |  |
| BOOM EXTENSION | OUT: | 41 s | IN: | 33 s |
| ROTATION | $90^{\circ}$ | 15.1 s |  |  |

ELECTRICAL REQUIREMENTS

| VOLTAGE | 12 VDC |
| :--- | :--- |
| CIRCUIT BREAKERS | $150 \& 200$ AMP |
| FUSE | 15 AMP |

NOTE: FUNCTION TIMES ARE BASED ON THESE INPUT VALUES

| PERIODIC MAINTENANCE SCHEDULE <br> MODEL 6036 CRANES |  |  |
| :---: | :---: | :---: |
| BOLTS |  |  |
| MOUNTING BOLTS | 7/8-9 GRADE 8 TORQUE 600 FT-LBS (DRY) | EVERY 4 MONTHS |
| BEARING BOLTS | 5/8-11 GRADE 8 TORQUE 220 FT-LBS (DRY) | EVERY 4 MONTHS |
| LUBRICATION |  |  |
| GREASE FITTINGS | SEE DRAWING 50048 | EVERY OTHER WEEK |
| HYDRAULIC FLUID | STANDARD <br> Chevron AW Hydraulic Oil 46 or equivalent SAE 15 weight oil <br> COLD WEATHER <br> AW 32 or equivalent SAE 10 weight oil | CHECK DAILY, FILL AS NEEDED |
| ROTATION GEARBOX | Sunco Prestige 740 EP or NLGI Grade 0 | EVERY MONTH |
| BEARING <br> (ZERK AND TEETH) | Oil Center Research PM 600 Military grease or equivalent Benton Based Grease NLGI Grade 2 | EVERY 6 HOURS OF OPERATION |

## CRANE LUBRICATION POINTS



## LIST FOR BOX, CRANE PARTS 6036DX-22 WP

Items with * have detailed DWG’s.

> P/N 29533 - BOX, CRANE PARTS 6036DX-22 WP DTCH, 18884 WINCH, VOLT METER

| 1) | P/N 29592 - MANUAL, CRANE 6036DX-22 WP..........................1pc |
| :---: | :---: |
| 2) | P/N 16878 - BREAKER, CIRCUIT 150 AMP ............................ 2 2pc |
| 3) | P/N 16923 - TERMINAL, LUG \#1/0 0.25 DIA.............................4pc |
| 4) | P/N 30766 - SWITCH, DISCONNECT...................................1pc |
| 5) | P/N 17010 - BRACKET, SWITCH MNT. ELE. CRN.....................1pc |
| 6) | P/N 17062 - TERMINAL, LUG \#1/0 GA 0.37 DIA........................4pcs |
| 7) | P/N 31837 - WIRE, BATTERY 1/0 X 30' W/MCN........................1pcs |
| 8) | P/N 15737 - TERMINAL, RING 1/0 GA 0.31 DIA....................... 2pcs |
| 9) | P/N 26084 - WIRE, GROUND 1/0 X 36" LONG......................... 1pcs |
| 10) | P/N MH*01143 - CAP, BREATHER 3/4 NPT-MONARCH............... 1pc |
| 11) | P/N 18600 - PLATE, CRANE-TRUCK STABILITY CHART...........1pc |
| 12) | P/N 28883 - DECAL, LOAD CAPACITY 36,000............................1pc |
| 13) | P/N 24846 - BREAKER, CIRCUIT 200 AMP .......................... 1pc |
| 14) | P/N 23144- LEVEL \& TAPE ASSEMBLY.................................1pc |
| 15) | P/N 27490 - SWITCH, DISCONNECT COVER PLATE................ 1pc |
| 16) | *P/N 28562 - BLOCK, TRAVEL 6.0K LBS/6.5D.........................1pc |


| ITEM | PART NUMBER | DESCRIPTION | QTY |
| :---: | :---: | :---: | :---: |
| 1 | 29529 | CRANE ASSY 6036DX-22 1ST | 1 |
| 2 | 29018 | EWH, DTCH ELEC WIFI PROP. WP | 1 |
| 3 | 28968 | PLATE, CONTROL SOCKET CAN MC | 1 |
| 4 | 30809 | SCREW, HHC 0.25-20 X 0.50 GR5 | 2 |
| 5 | 30889 | WASHER, LOCK 0.25 GR5 PLATED | 2 |
| 6 | 28791 | CONTROL, FM RECEIVER GUIDER WP | 1 |
| 7 | 29026 | SPACER, RECEIVER 1.75" | 4 |
| 8 | 29043 | SCREW, HHC 0.25-20 X 3.00 GR8 | 4 |
| 9 | 31110 | WASHER, FLAT 0.25 GR5 PLATED | 4 |
| 10 | 30833 | NUT, HEX NYLOC 0.25-20 GR2 | 4 |
| 11 | 28965 | TUBE, HEAT SHRINK 0.75 DIA ADH (1.5 LG) | 2 |
| 12 | 17063 | TERMINAL, LUG \#1 GA 0.37 DIA | 2 |
| 13 | 30674 | BOOT, RUBBER 1 \& $1 / 0$ | 2 |
| 14 | 22103 | SCREW, MH RD 4-40 X 0.50 ZINC | 4 |
| 15 | 22105 | WASHER, LOCK \#4 ZINC-PLATED | 4 |
| 16 | 22104 | NUT, HEX 4-40 ZINC-PLATED | 4 |
| 17 | 28853 | INCLINOMETER, BOOM ANGLE CAN | 1 |
| 18 | 28963 | SCREW, SOC HD 8-32 X 0.37 SS | 2 |
| 19 | 17882 | WASHER, LOCK \#8 GR2 PLATED | 2 |
| 20 | 28034 | PLATE, COVER VOLT/AMP SLOT- MC | 1 |
| 21 | 17164 | SCREW, SOC HD 10-24 X 0.62 SS | 2 |
| 22 | 32639 | WASHER, LOCK \#10 GR2 PLATED | 2 |
| 23 | 28175 | COVER, 6036 CONT. \& SOLENOIDS | 1 |
| 24 | 26582 | SCREW, SOC HD 0.25-20 X 0.37SS | 6 |
| 25 | 29299 | WASHER, LOCK 0.25 STAR SS | 1 |
| 26 | 28597 | WIRE, BATTERY \#4 X 8" W/TRM | 1 |
| 27 | 28690 | WASHER, LOCK 0.25316 SS | 1 |
| 28 | 34069 | SCREW, HHC 0.25-20 X 0.50 SS | 1 |
| 29 | 70041 | NUT, HEX 0.44-20 GR2 | 1 |
| 30 | 24432 | VALVE, 4W/3P/12V/OC DTCH | 3 |
| 31 | 30956 | SCREW, SOC HD 10-24 X 2.00 | 12 |
| 32 | 22986 | ROPE, WIRE 0.31 X 90' W/THB\&LP | 1 |
| 33 | 32589 | SCREW, HWHSMS 0.25-20 X 0.75 | 4 |
| 34 | 18310 | DECAL, WARNING TAG -DO NOT EXT | 1 |
| 35 | 28794 | TRANSDUCER, PRESSURE 5000 PSI | 1 |
| 36 | 24960 | CLAMP, HOSE SUPPORT 0.25 ID | 5 |
| 37 | 28126 | SCREW, SOC HD 0.25-20 X 0.25SS | 5 |
| 38 | 23755 | DECAL KIT 6036DX-22 | 1 |
| 39 | 25704 | TAPE, REFLECTIVE 6"WHITE/6"RED X 75" | 4 |
| 40 | PFORM81 | TEST, SHEET 6036DX REV-A | 1 |
| 42 | PFORM134 | FM INSTRUCTIONS 28790, 28791 | 1 |

ITEM WITH (*) IS LOCATED IN BOX PARTS.

 - RUN CORD REEL AND INCLINOMETER WIRES THRU CLAMPS. HAND TIGHT.













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| ITEM | PART NUMBER | DESCRIPTION | QTY |
| :---: | :---: | :---: | :---: |
| 1 | 28427 | HOUSING WELDMENT 6036DX | 1 |
| 2 | 27128 | REDUCER, SPEED PERFECTION GEAR | 1 |
| 3 | 30787 | BEARING, GEAR 25/5000, 36/6036 | 1 |
| 4 | 15677 | SPACER, SPEED REDUCER REAR MC | 1 |
| 5 | 17472 | O-RING, 158 BUNA 70 DUROMETER | 1 |
| 6 | 17473 | O-RING, 155 BUNA 70 DUROMETER | 1 |
| 7 | 18322 | SWIVEL, ELEC ASSY 5000W/6036W | 1 |
| 8 | 18336 | PLATE, BASE 25K/36K CR-NOTCHED | 1 |
| 9 | 18393 | BRACKET, SWIVEL STOP 5000W | 1 |
| 10 | 19021 | WIRE, SUPPLY ELEC 5000W/6036W | 1 |
| 11 | 22406 | SCREW, DRIVE | 2 |
| 12 | 22831 | COVER, SWIVEL ELECTRIC | 1 |
| 13 | 23389 | PLATE, SERIAL NO. MACHINING | 1 |
| 14 | 27332 | RING, ECCENTRIC PERFECTION GEA | 1 |
| 15 | 28429 | SCREW, HHC 0.43-14 X 2.50 GR8 | 4 |
| 16 | 28643 | WIRE, GROUND BASE PLATE | 1 |
| 17 | 30457 | SCREW, HHC 0.25-20 X 0.75 GR5 | 2 |
| 18 | 30810 | SCREW, HHC 0.25-20 X 1.00 GR5 | 4 |
| 19 | 30865 | SCREW, HHC 0.62-11 X 2.00 GR8 | 37 |
| 20 | 30876 | SCREW, SOC HD 0.62-11 $\times 2.00$ | 5 |
| 21 | 30888 | WASHER, FLAT 0.31 GR5 PLATED | 1 |
| 22 | 30889 | WASHER, LOCK 0.25 GR5 PLATED | 7 |
| 23 | 30890 | WASHER, LOCK 0.31 GR5 PLATED | 3 |
| 24 | 30972 | WASHER, LOCK 0.43 GR5 PL | 4 |
| 25 | 31042 | NUT, HEX NYLOC 0.31-18 GR2 | 1 |
| 26 | 31054 | WASHER, FLAT 0.62 SAE GR8 | 42 |
| 27 | 31062 | WASHER, FLAT 0.43 SAE GRADE 8 | 4 |
| 28 | 31110 | WASHER, FLAT 0.25 GR5 PLATED | 4 |
| 29 | 31437 | COVER, SIDE 25K/36K/50K PC | 1 |
| 30 | 32117 | SPACER, SPEED REDUCER FRONT MC | 1 |
| 31 | 32957 | CLAMP, HOSE SUPPORT 0.62 ID | 1 |
| 32 | 33608 | SCREW, SOC HD 0.25-20 X 0.75 | 1 |
| 33 | GP-535-10117-1 | ZERK, 0.12 NPT STRAIGHT | 1 |





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| :---: | :---: | :---: | :---: |
|  | $\begin{array}{\|l\|} \hline \text { DRWN BY: AT } \\ \hline \text { DAIE: } 1011615 \\ \hline \end{array}$ | BOOM, INNER ASSY 6036DX-22 | 27599-D |

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WINCH DC3000-12VDC P/N 18884


## SERVICE PARTS LIST: DC3000 HOIST-12V P/N 18884

ITEM REFERENCE

1. (MTO)S/P ELECTRIC MOTOR, 12VDC
2. DRUM SUBASSY, DC3000
3. BUSHING DRUM NYLATRON
4. (KB) SET SCREW, DOG POINT, M10
5. WASHER, THRUST, NYLATRON, CIM
6. (MTO)S/P DRUM SUPPORT ASSY
7. GASKET, RING GEAR
8. 
9. 

10
11. CARRIER ASSY, 2ND STG, 31T PLT
12.
13.
14.
15.
16.
17.
18.
19.
20.

ITEM / KIT No.

WI*31681
WI*39924
WI*30274
WI*36974
WI*30277

WI*31675
WI*14964

WI*37188
WI*18336
WI*33413
WI*33417
WI*27837
WI*19574
WI*31680
WI*85581
WI*62797
WI*1448

WI*37467
WI*85582
WI* 13455


CAUTION:
NEVER USE A HOOK WHOSE THROAT OPENING HAS BEEN INCREASED, OR WHOSE TIP HAS BEEN BENT MORE THAN
10 DEGREES OUT OF PLANE FROM THE HOOK BODY, OR IS IN ANY WAY DISTORTED OR BENT
THIS DRAWING INTENTIONALLY LEFT BLANK
FOR FUTURE ADDITIONS
OR
A PART OR FEATURE IS NOT APPLICABLE TO THIS CRANE


## LIFTMOORE LIMITED WARRANTY

Parts and Structural

Liftmoore, Inc. warrants each LIFTMOORE crane to be free from defects in materials and workmanship for twelve (12) months from the date of delivery to the original customer. Under the terms of this warranty the crane structural components manufactured by LIFTMOORE, Inc. are warranted for thirty-six (36) months from the date of delivery to the original customer. LIFTMOORE, Inc. will repair or replace, as its sole discretion, any equipment or part that is returned f.o.b. to LIFTMOORE, Inc.'s plant at 7810 Pinemont Drive, Houston, Texas 77040, or to one of its authorized dealers, and is found by LIFTMOORE, Inc. or its authorized dealer to have been defective at the time of original delivery.

The foregoing warranty is the exclusive warranty made by LIFTMOORE, Inc. with respect to its cranes and is in lieu of all other warranties. ANY AND ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, INCLUDING ANY WARRANTY OF MERCHANTABILITY OR FITNESS OF ANY CRANE FOR A PARTICULAR PURPOSE OR OPERATION, ARE HERBY EXPRESSLY DISCLAIMED.

The foregoing warranty applies only to LIFTMOORE cranes under normal use and service and does not apply in the event of damage caused by repair or alteration or damage during shipment, accident, negligence, overloading, or misuse, including operator's failure to follow any of the instructions issued with the crane.

This warranty is limited to the original purchaser and is not assignable. In order to submit a claim, the original purchaser must provide a copy of the original invoice for the crane in question within twelve (12) months following the delivery date and within 30 days from the date of repair.

The warranty applies only when the LIFTMOORE crane is used for commercial purposes and does not cover any purchase for use for personal, family or household purposes.

LIMITATION OF LIABILITY: LIFTMOORE, Inc.'s liability for any losses or damages resulting from any cause whatsoever, including LIFTMOORE, Inc.'s NEGLIGENCE or from a defective crane irrespective of whether such defects are discoverable or latent, shall in no event exceed the purchase price of the crane to which losses or damages are claimed, or at the election of LIFTMOORE, Inc., the repair or replacement of the defective crane.

In no event shall LIFTMOORE, Inc. be liable for any special, incidental, or consequential damages, including commercial losses or costs of any kind sustained by purchaser or any other person or for any damages for which purchaser may be liable to other persons by reason of any defect in any LIFTMOORE crane or any part thereof.

LIFTMOORE, Inc. reserves the right to make changes in design or construction of its cranes at any time without obligating itself to make such changes on cranes previously manufactured.

No agent, employee, or representative of LIFTMOORE, Inc. has authority to amend or modify the foregoing warranty or to bind LIFTMOORE, Inc. by any other warranty, guaranty, or assumption of liability.

In the event any provision of this warranty is for any reason held ineffective, the remaining provisions shall remain in full force and effect.

Some states do not allow limitations on how long an implied warranty lasts or the exclusion or limitation of incidental or consequential damages, so the above limitations and exclusions may not apply to you. This warranty gives you specific legal rights, and you may also have other legal rights that vary from state to state.


[^0]:    ${ }^{1}$ The CAN control will only work with the CRANE module. The ENGINE module only works on RF

